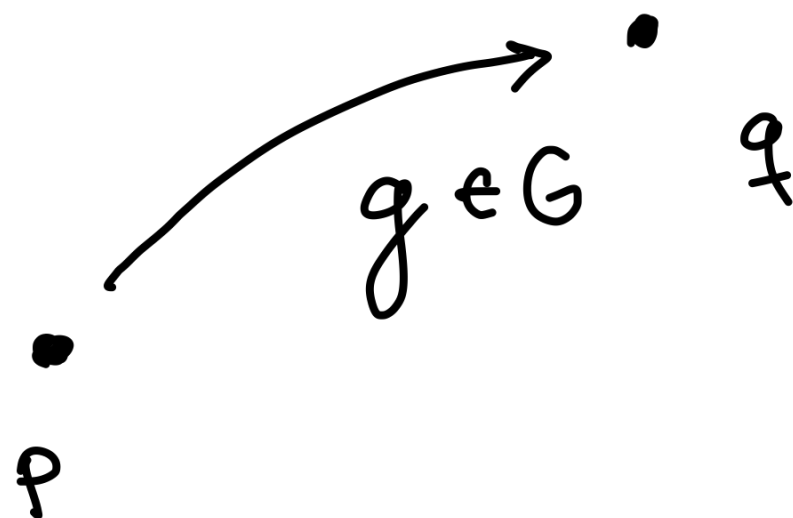


Deforming Geometric Structures in Low Dimensions

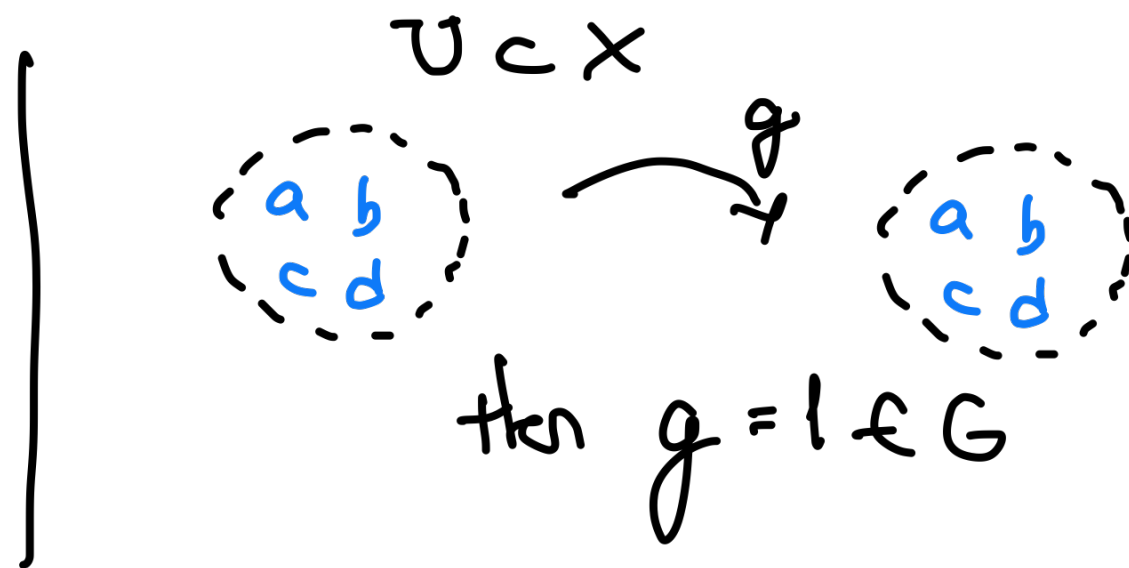
$H^g \mathbb{E}^l$ - Community Seminar 2025

Charles Daly - M.P.I Leipzig

05.11.2025



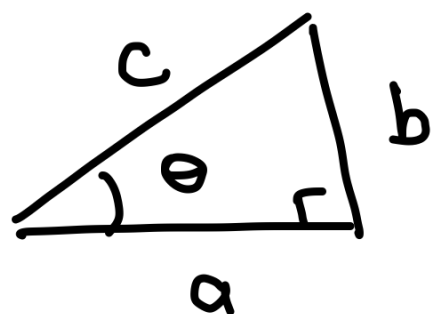
What is a Geometry?
 think of geometry as a pair
 (G, X) G acts transitively
 and strongly effectively on X .



Euclidean

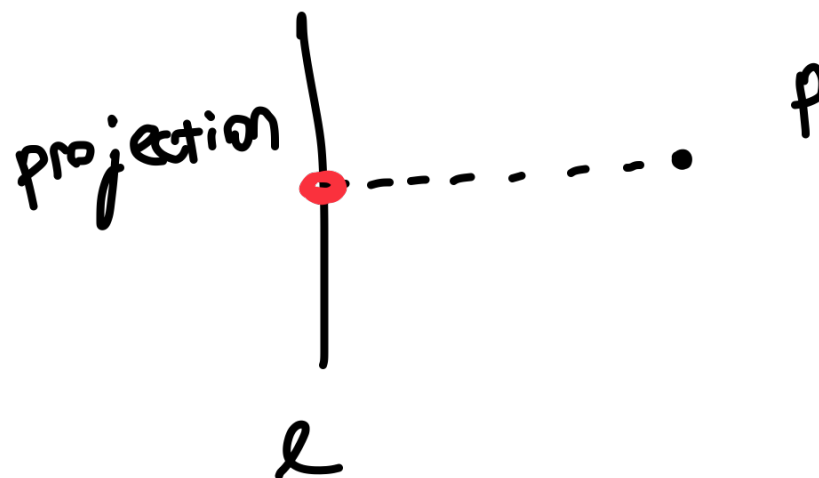
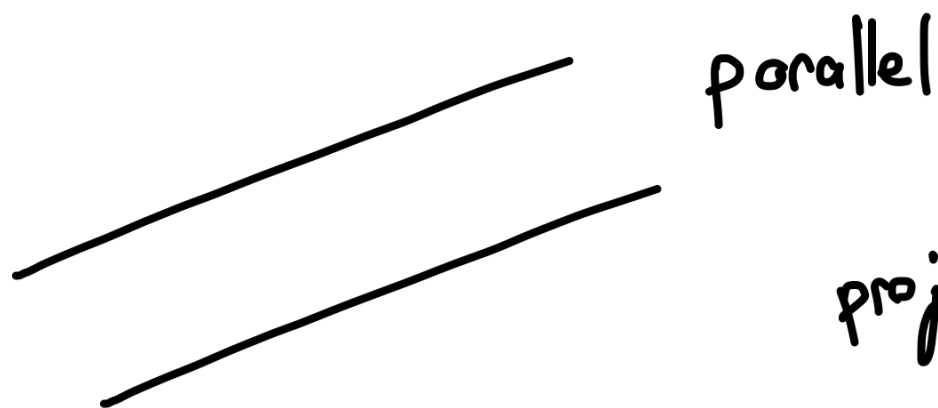
$$G = \text{Isom}(\mathbb{E}^2)$$

$$X = (\mathbb{E}^2, \|\cdot\|_2)$$



$$a^2 + b^2 = c^2$$
$$\sin \theta = b/c$$

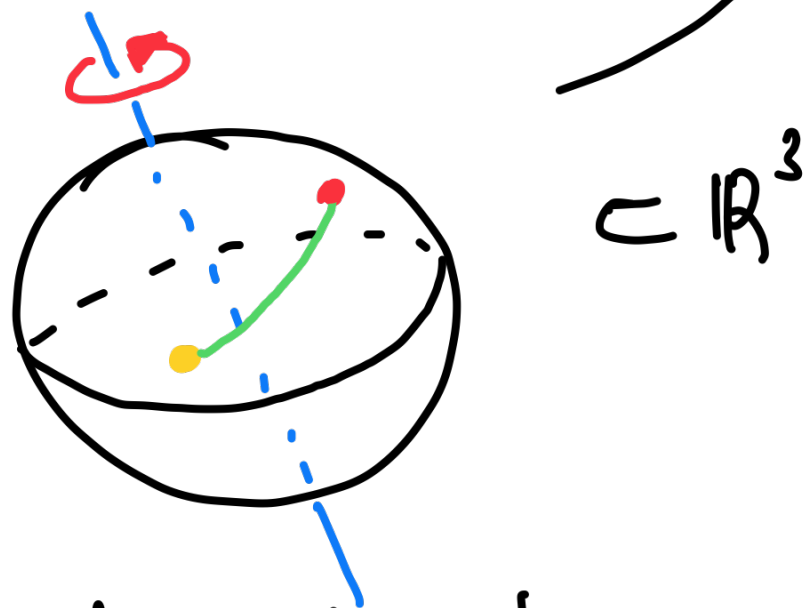
$$\text{Area} = \frac{1}{2} (\text{base}) (\text{height})$$



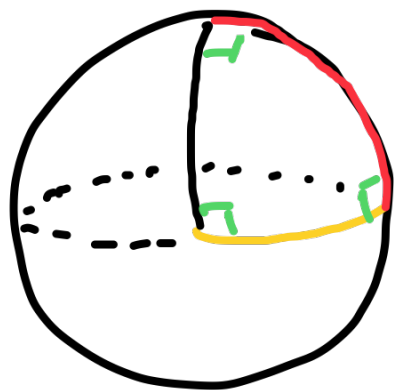
(Spherical)

$$G = O(3, \mathbb{R})$$

$$X = S^2$$



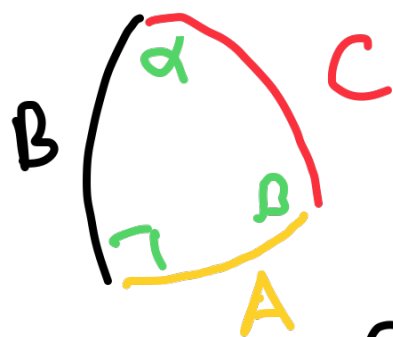
$$\subset \mathbb{R}^3$$



triangles still a thing
angle sums all greater than π

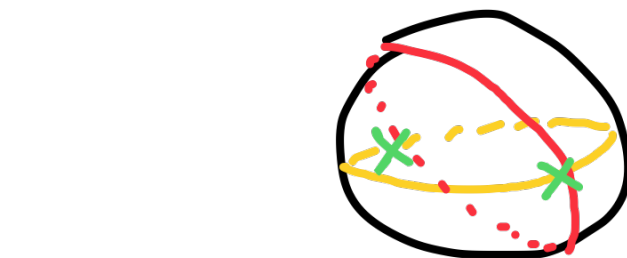
$$\text{area}(\text{triangle}) = \frac{\pi}{2}$$

more generally Area = ($\sum$ angles - π)



$$\cos(C) = \cos(A)\cos(B)$$

point projection gets funky

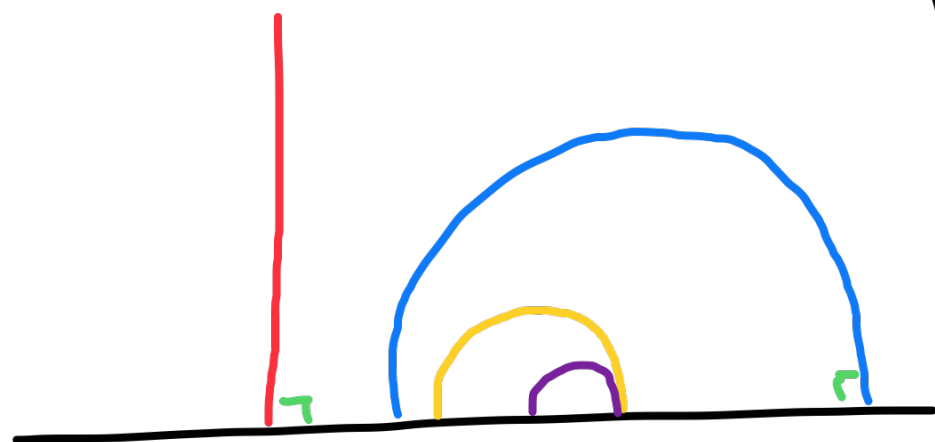


parallel out window is



Hyperbolic

$\mathbb{H}^2$

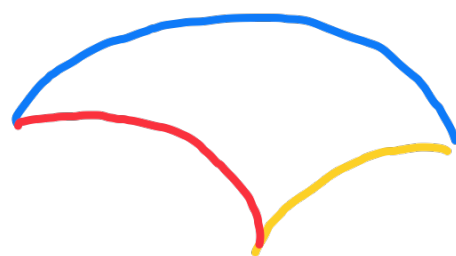


parallelism makes sense

$\nearrow$ ultra-parallel  & 
 $\searrow$ (asymptotically) parallel  & 

Area of $\Delta = \pi - \sum \text{angles}$

triangle



$$G = \text{PGL}(2, \mathbb{R})$$

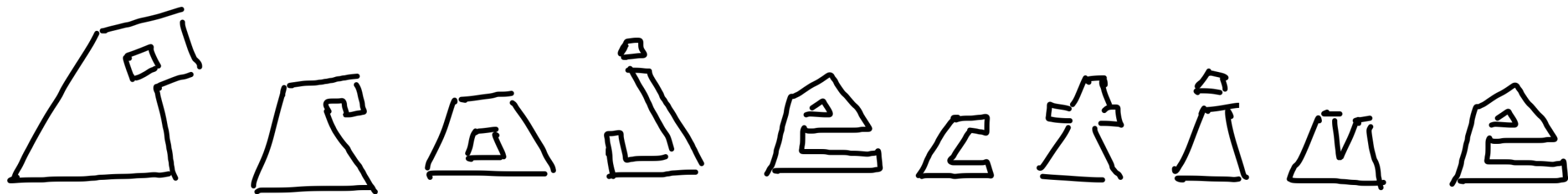
$$X = \mathbb{H}^2$$

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix} z = \frac{az+b}{cz+d}$$

lines are semi-circles
 $\perp$ to real axis, or, vertical
 lines.

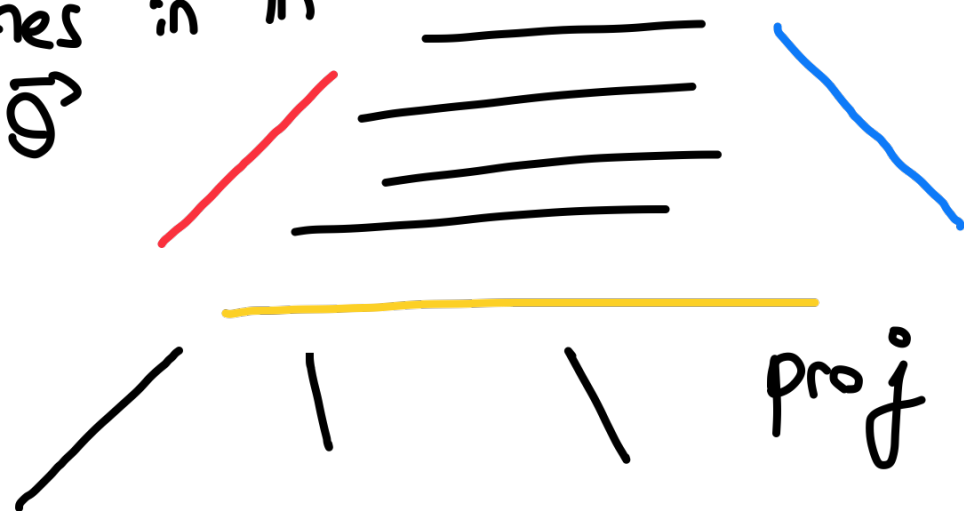
$$\partial \mathbb{H}^2 \simeq \bigcirc$$

$$\text{Area} \left(\text{triangle} \right) = \pi$$



$X = \mathbb{RP}^2 =$ space of lines in $\mathbb{R}^3$
through $\vec{0}$

$$G = \text{PGL}(3, \mathbb{R})$$



unifies all 3-geometries
however, loses metric in
process.

$$x^2 + y^2 = 1 \approx x^2 - y^2 = 1 \approx y - x^2 = 1$$

$$\bigcirc \approx \text{hyperbola} \approx \cup \quad \text{in } \mathbb{RP}^2$$

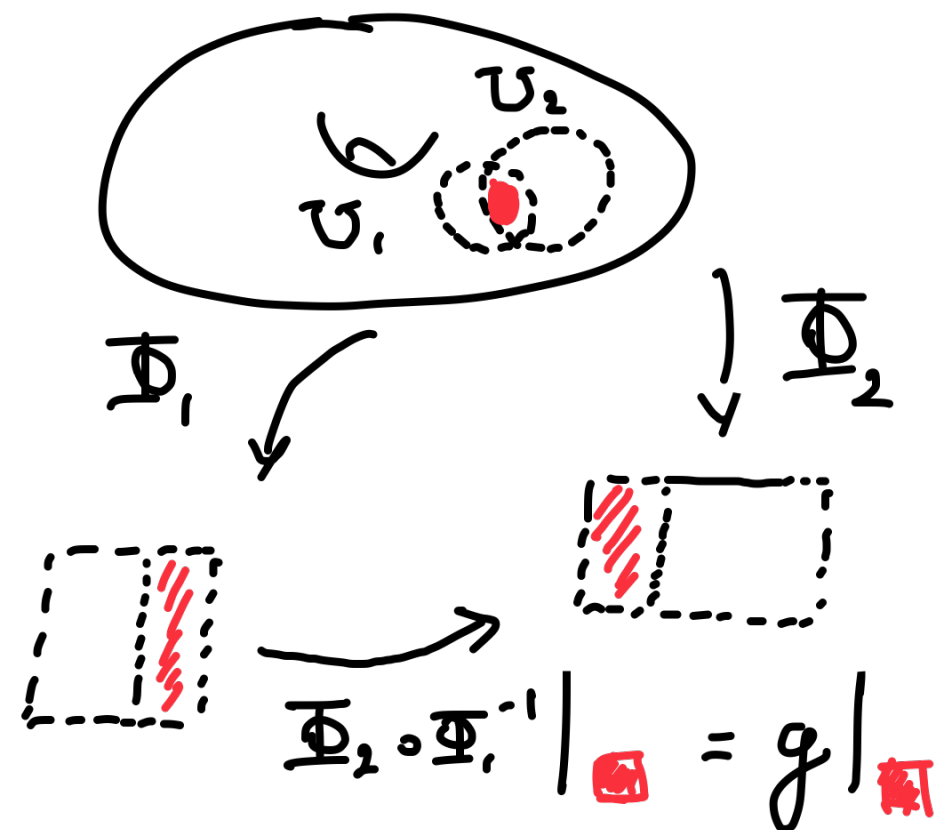
Geometric Structure on Manifold

Let (G, X) be a geometry and M a manifold.

A (G, X) -structure on M is a collection of charts $U_\alpha \subset M \xrightarrow{\Phi_\alpha} X$ so that locally coordinate

changes are symmetries in G .

this means locally M is modelled by the geometry (G, X) .

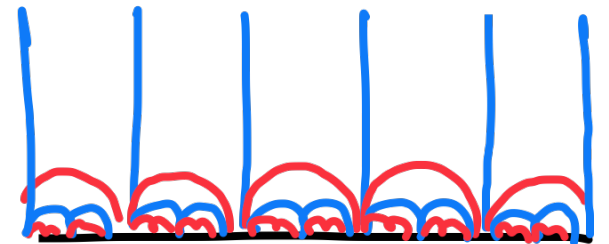
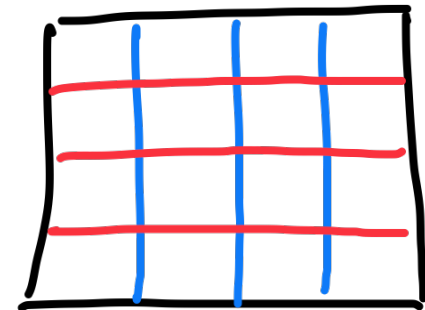
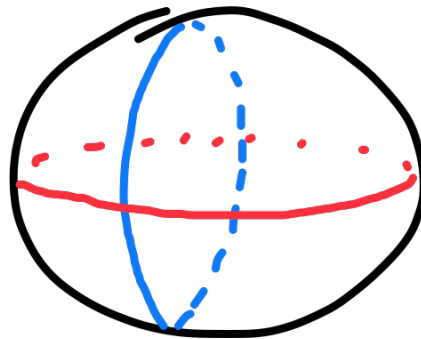
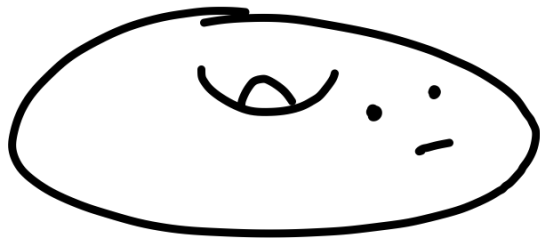


Question

One:

1. Given a manifold M , what type of (G, x) structures can it admit?

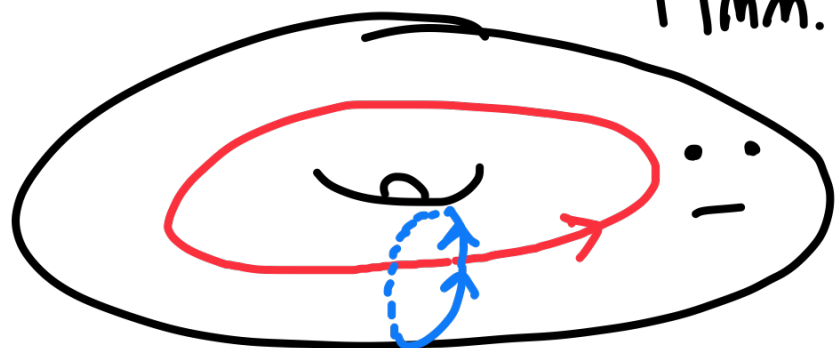
Hmm... Which outfit fits...?



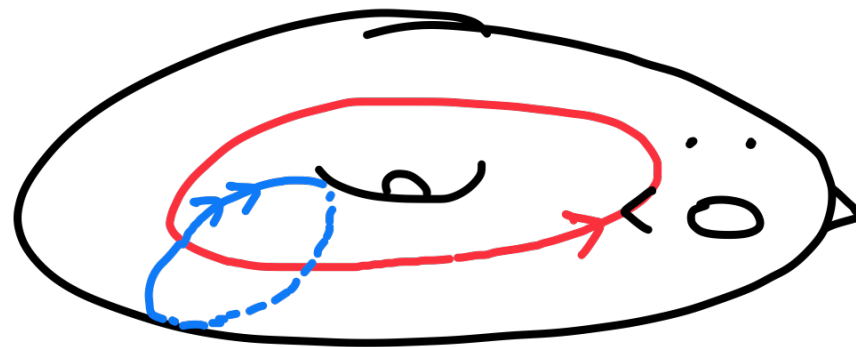
Question Two

2. If you can put a (G, X) -structure on M , how many inequivalent ways can you do it?

Hmm... 20 €...

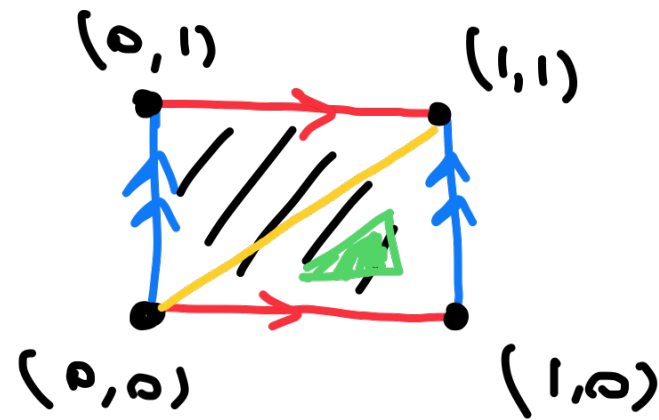


30 €?! They're practically the same!



$\mathbb{E}$ ample

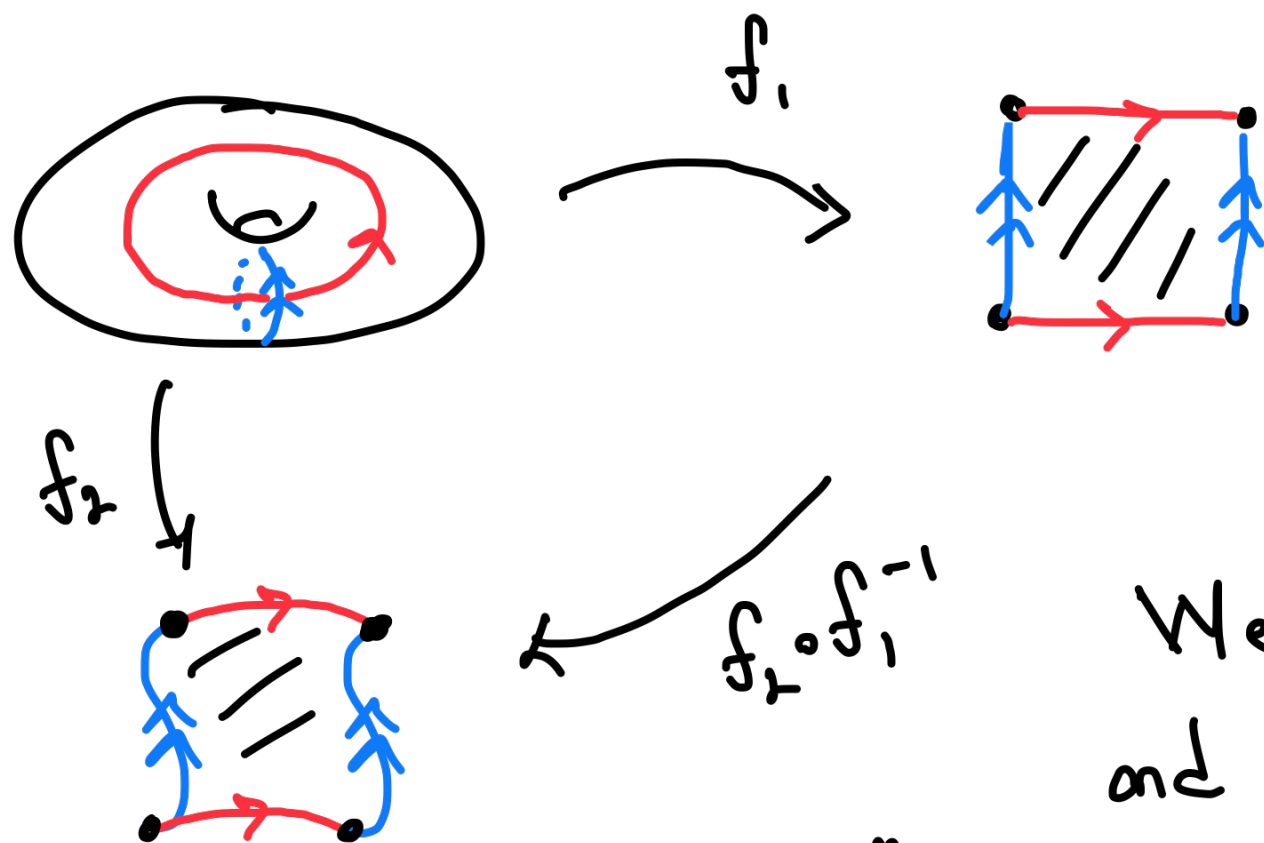
$M =$



Gives T^2 a euclidean structure. So on T^2 we can define a notion of a line. We can also say when something is a triangle on T^2 . Area, length, angles, parallelism, etc are all inherited on our torus.

Example (cont)

Want to consider structures up to some equivalence



f_1 and f_2 defining
Some Euclidean structure
on T^2 (pretty much)

We say $f_1: T^2 \rightarrow (S_1, g_1)$

and $f_2: T^2 \rightarrow (S_2, g_2)$ are equivalent

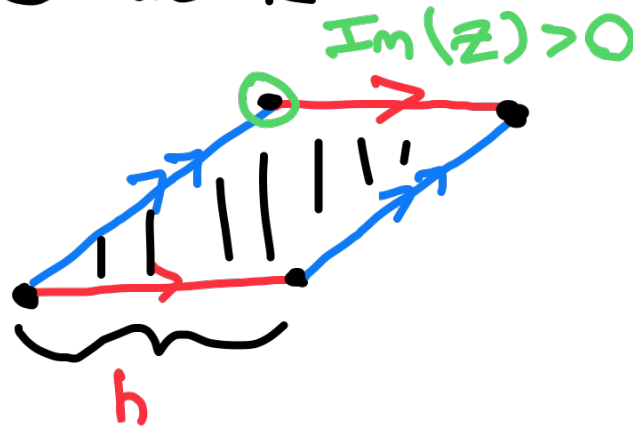
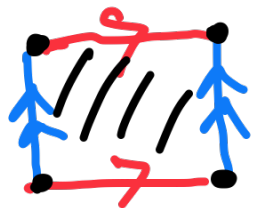
iff $f_2 \circ f_1^{-1}: (S_1, g_1) \rightarrow (S_2, g_2)$ is isotopic
to an isometry

f_1, f_2 called markings

Example continued

Study space of (Marked) (G, X) -structures on manifold up to equivalence, $X(M)$.

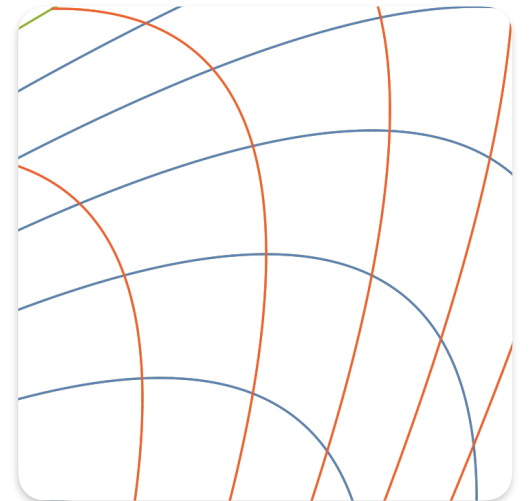
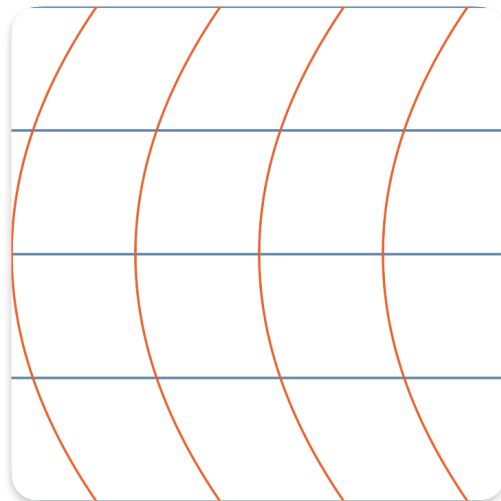
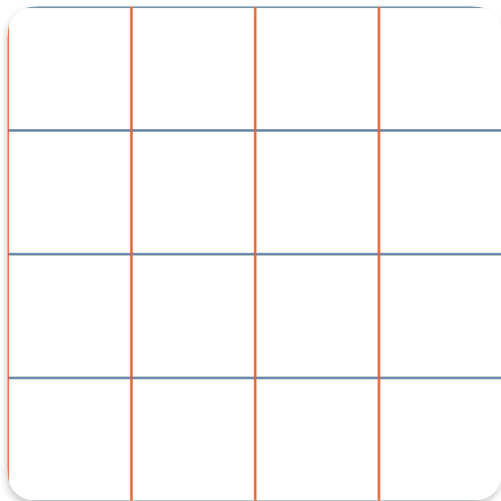
For T^2 we can think of space of marked Euclidean structures as space of parallelograms with one edge horizontal and other edge above horizontal axis.



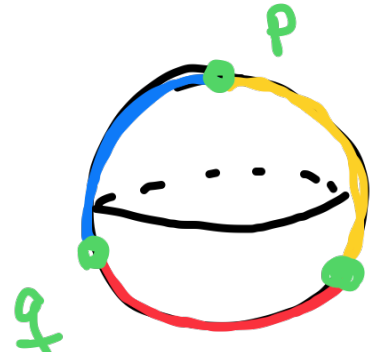
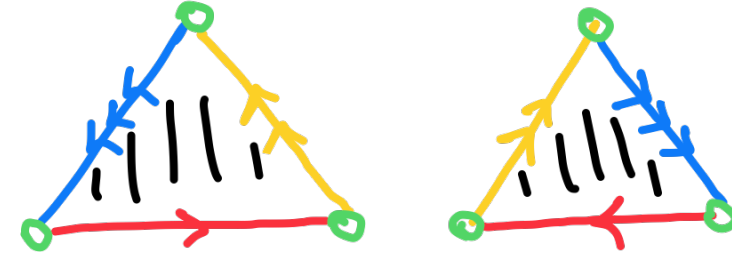
quick dimension count
gives 3 real.

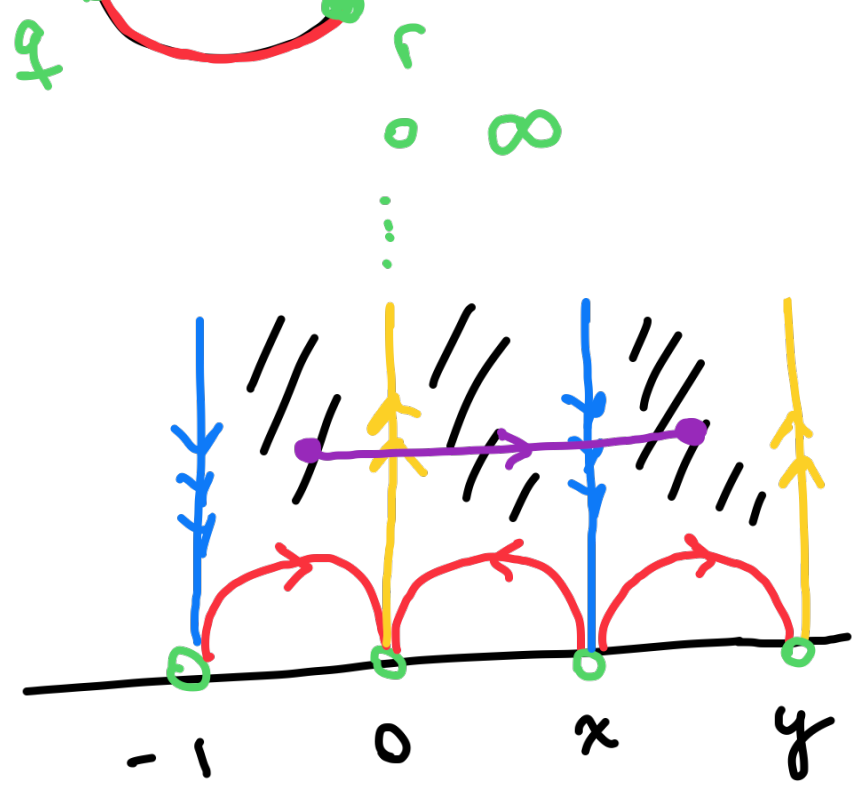
What about non-Euclidean T^2 ?

A particularly nice feature of the Euclidean tori is they're quotients of $\mathbb{R}^2$ by discrete subgroups of $\text{Isom}(\mathbb{E}^2)$. What about $\text{Aff}(\mathbb{A}^2) \cong \text{GL}(2, \mathbb{R}) \ltimes \mathbb{R}^2$ $\text{A}^2_{\text{comp}}(T^2) \cong \mathbb{R}^2$ where origin corresponds to all Euclidean structures on T^2 . (BG)

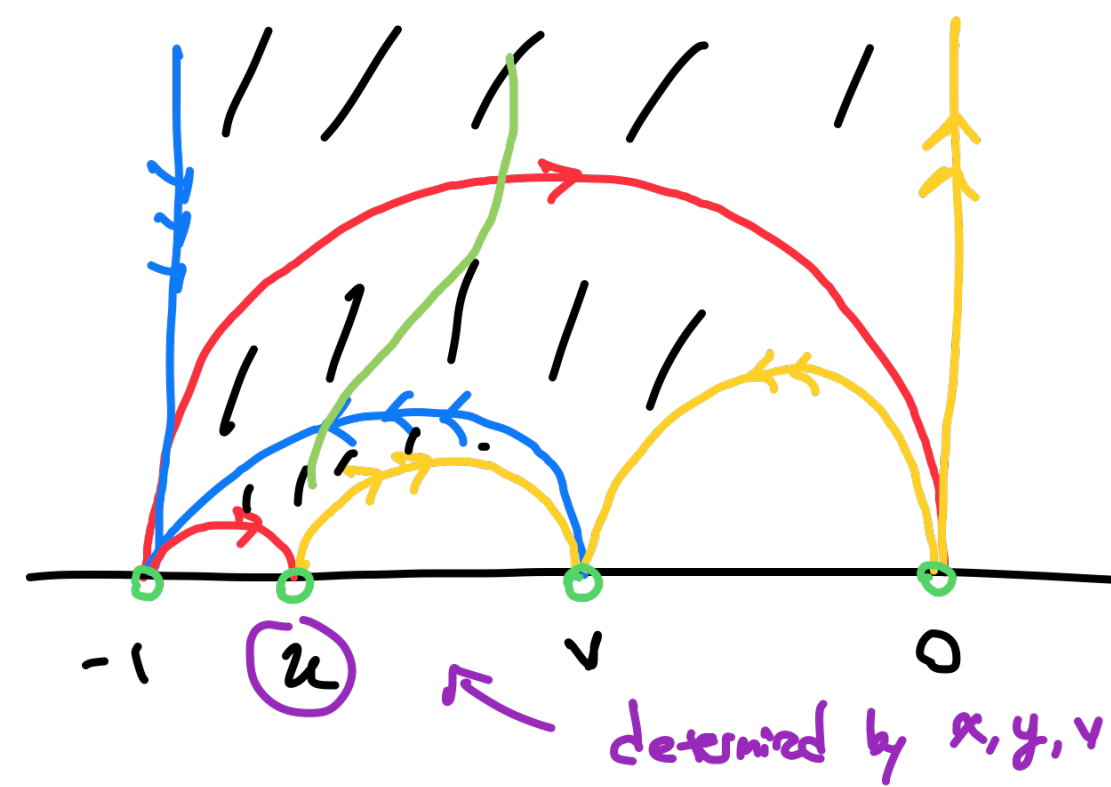


Another Example

$M =$  $\setminus \{p, q, r\}$, Topologically $M =$ 

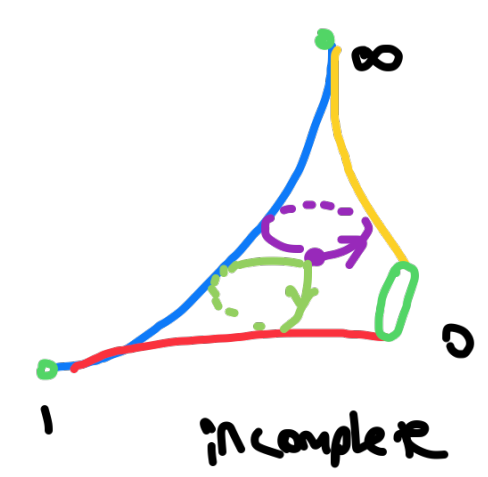
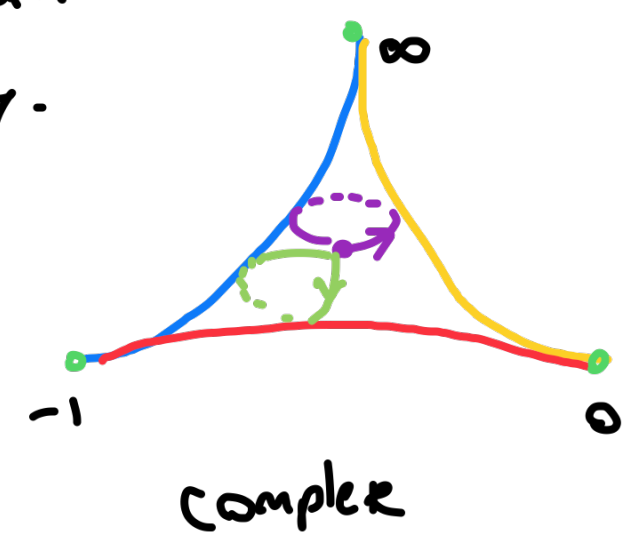


and

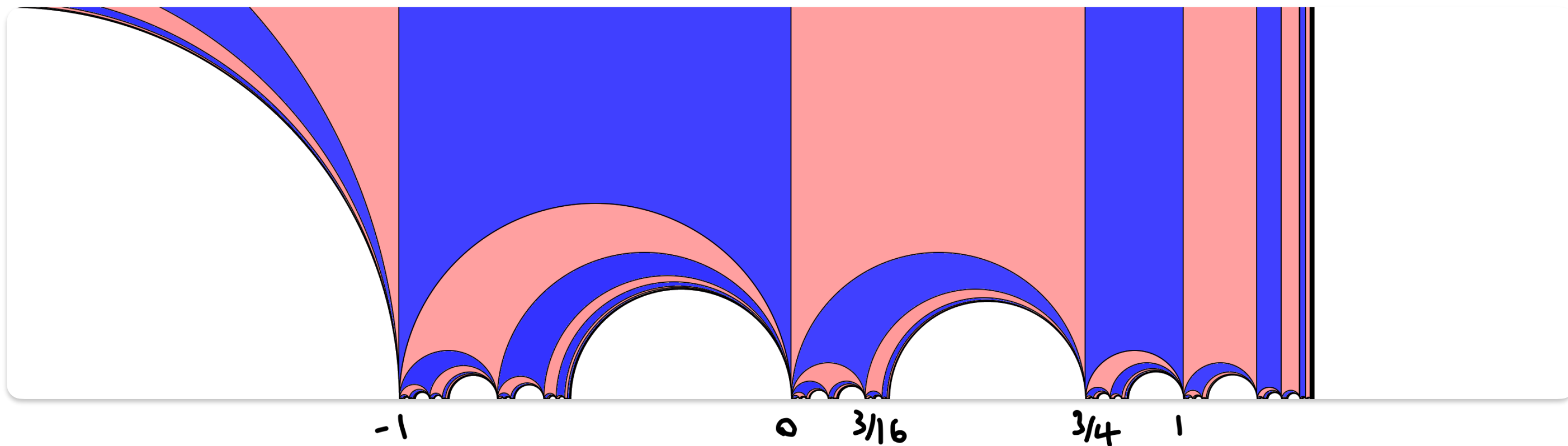
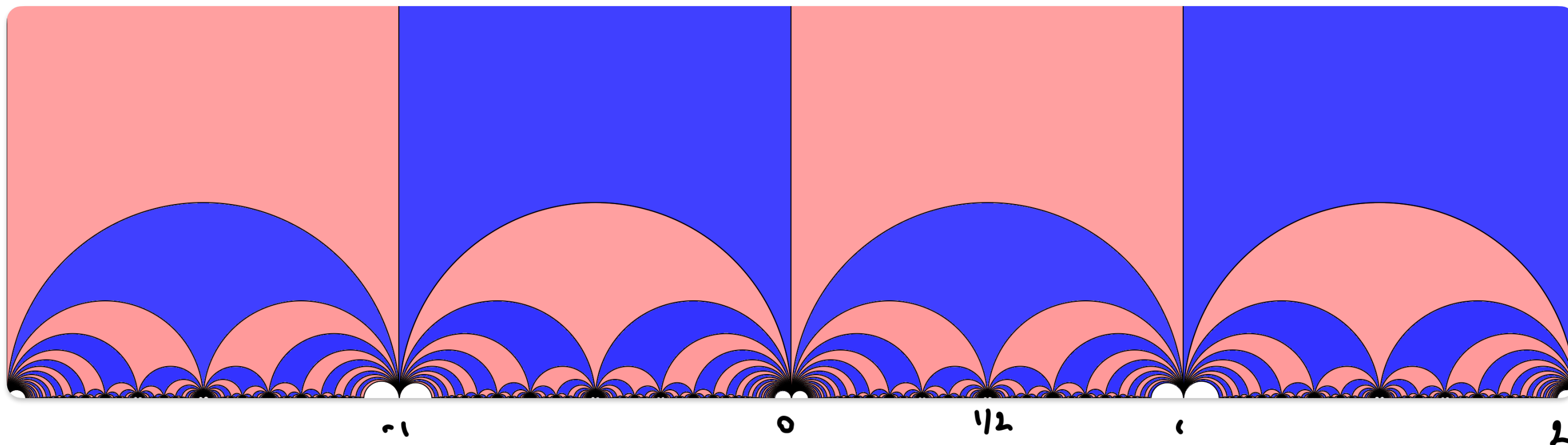


Complete structure if all geodesics extend indefinitely.

$H^2(M)$ locally 3 dimensional.



Some Hyperbolic Structures on $S^2 \setminus \{p, q, r\}$



Ehresmann - Weil - Thurston

To each (G, X) -structure we assign on M up to equivalence, we obtain a representation of the fundamental group, $\pi_1(M, p) \xrightarrow{\text{hol}} G$ called holonomy map. Well defined up to conjugation

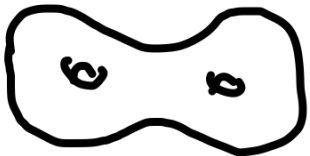
get a map

$$\frac{\{ \text{Marked } (G, X)\text{-structures on } M \}}{\text{Equivalence}} \xrightarrow{\text{Hol}} \frac{\text{Hom}(\pi_1(M, p), G)}{G}$$

Ehresmann - Weil - Thurston

$\text{Hom}(\pi_1(M, p), G)/G := \mathcal{X}(\pi_1(M, p), G)$ called
Character variety. Many tools used to
study it and its topology.

A lot is known if ---

$M = \text{surface}$  and $G = \text{PSL}(2, \mathbb{R})$

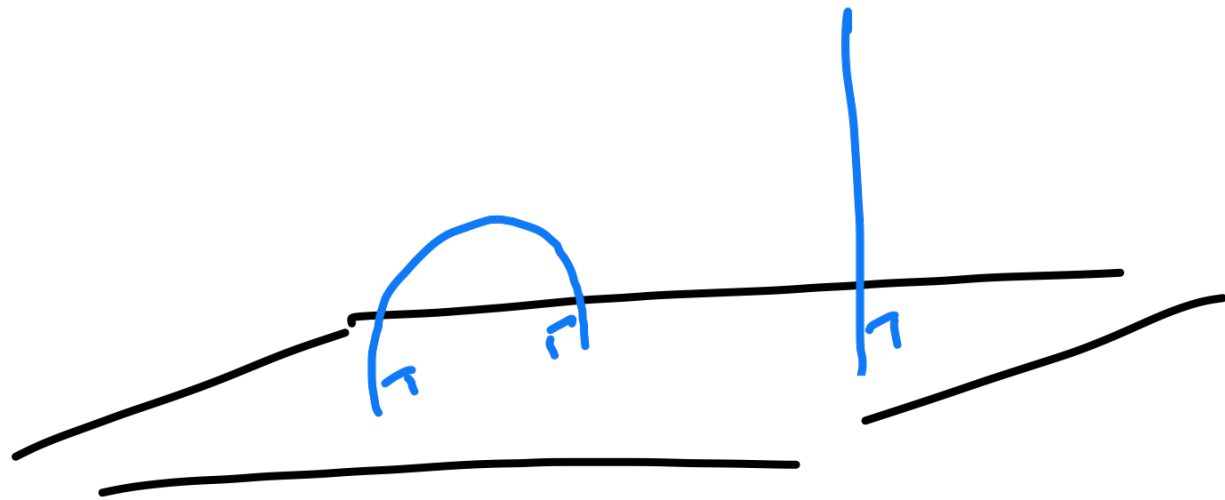


with or
without ∂M

For example in this case $\mathcal{X}(\pi_1(M, p), G)$ has
finitely many components.

Hyperbolic 3-manifolds

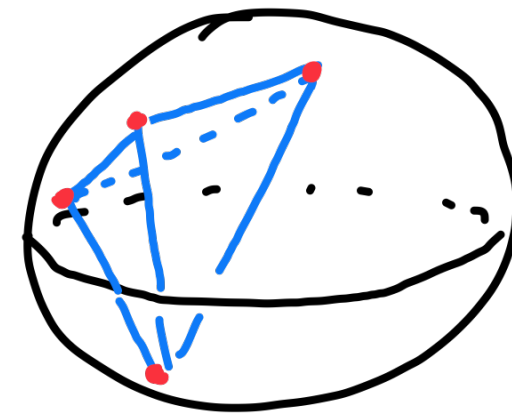
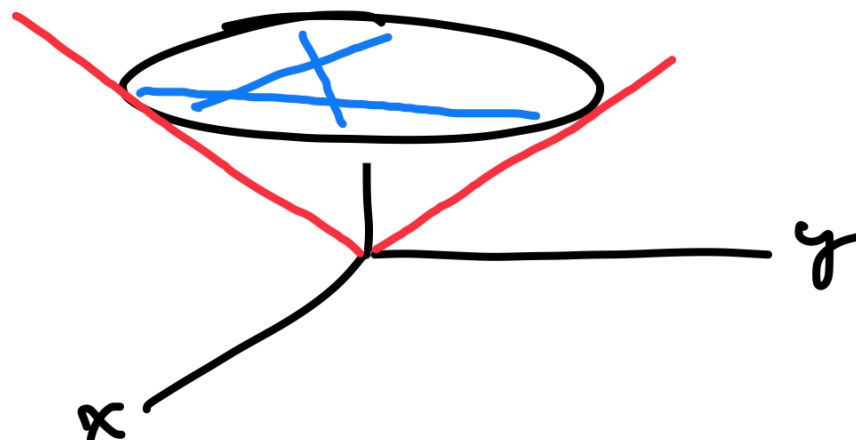
Geometric manifolds with $G = \mathrm{PSL}(2, \mathbb{C})$ and $X = \mathbb{H}^3$
 $\mathbb{H}^3$, where $\partial \mathbb{H}^3 \cong \mathbb{CP}^1$



Can also think of as
 $\mathrm{Proj}(\vec{x} \in \mathbb{R}^{3,1} \mid \langle \vec{x}, \vec{x} \rangle < 0) = K^3$
 with $G = \mathrm{PSO}(3,1)$

K^2 for illustration
 $|z|$

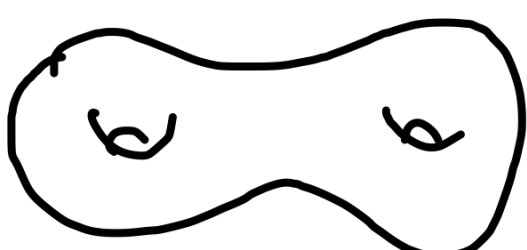
Projectivize
 $x^2 + y^2 - z^2 < 0$

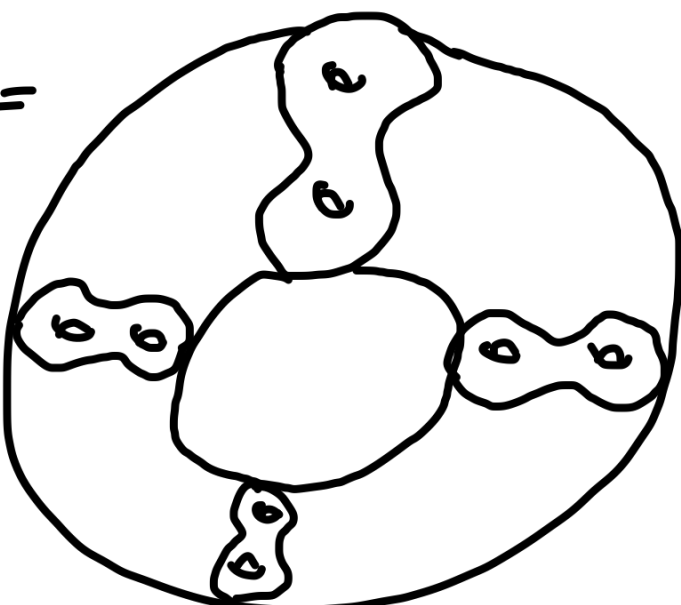


K^3 in affine
 chart of $\mathbb{RP}^3$

Where find these?

$M = S^3 / \langle \Sigma \rangle$ famously has a hyperbolic structure.

More generally, $S =$ , $\phi =$ free pseudo anosov

then form $M_\phi =$  mapping torus of ϕ .

By Thurston's Hyperbolization,
 M_ϕ admits a hyperbolic
structure.

Question :

How many such hyperbolic structures on M are there?

Mostow Rigidity : Let M be an orientable 3-manifold.

Any two complete finite volume hyperbolic structures on M are in fact isometric.

EWT : $\frac{H^3_{\text{complete}}(M)}{\text{E equivalence}} \xrightarrow{\text{Hol}} \mathcal{X}_{\text{comp}}(\pi_1(M, p), \text{PSL}(2, \mathbb{C}))$
at complete structure is a point.

What about incomplete?

Thurston's Dehn-Filling says deformation space locally

$\mathbb{C}^{\# \text{ of cusps} - \text{dimensional}}$.

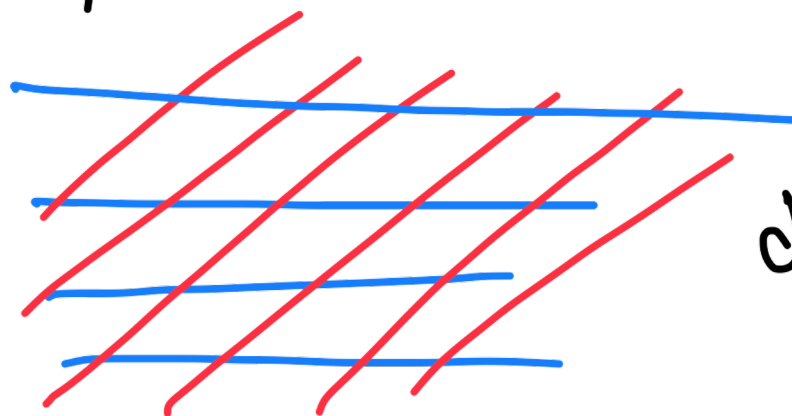
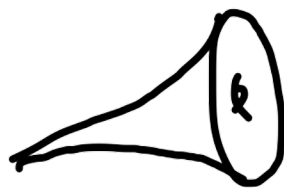
if $M =$



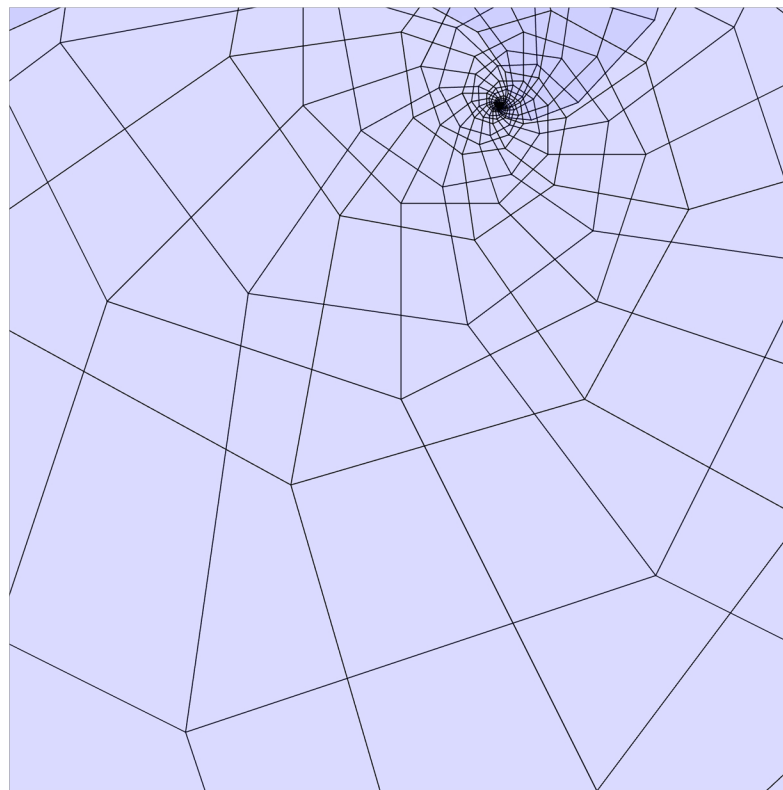
+
compact
stuff

then

$H^3(M)$ locally $\cong \mathbb{C}^3$ around
complex hyperbolic structure.



∂H^3



What about Projective Deformations?

Every hyperbolic structure is naturally a projective one.

$$(K^3, \mathrm{PSO}(3,1)) \hookrightarrow (\mathbb{RP}^3, \mathrm{PGL}(4,\mathbb{R}))$$

Fundamental Question:

Does M admit projective deformations of its hyperbolic structure? If not we say M is projectively rigid.

State of the Art

If M is compact, the answer is typically no
(unless M has a totally geodesic embedded surface)
CL(Th): Census manifolds admit at most 61 of 4,500 or so.

If M cusped, the answer is maybe
CL(Ti): So long as the cusps can deform and preserve
convex subset of $\mathbb{RP}^3$, then yes, however
explicit calculations are difficult.

State of the Art (cont)

There's a cohomological condition known as
inf. proj. rigidity. rel cusp, (HP),

$$H^1(M; \mathbb{SL}_4 \mathbb{R} \text{ Ad}_\rho) \xrightarrow{\text{res}} H^1(\partial M; \mathbb{SL}_4 \mathbb{R} \text{ Ad}_\rho)$$

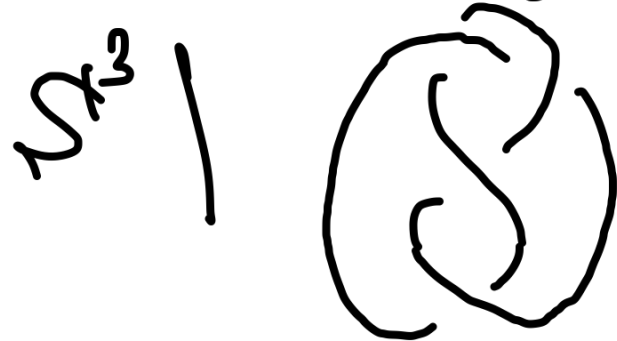
Under this condition, M guaranteed to admit projective
deformations and $2M$ admits a (very nice type of)
projective structure (BDL).

And if M is (iprc) infinitely many Dehn-Surgeries on
 M are projectively rigid (HP).

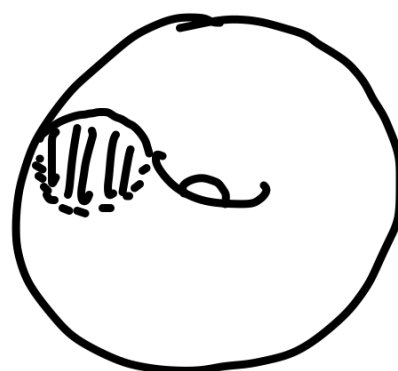
Some My Work

2000 or so Dehn-Surgeries of fig. eight-knot

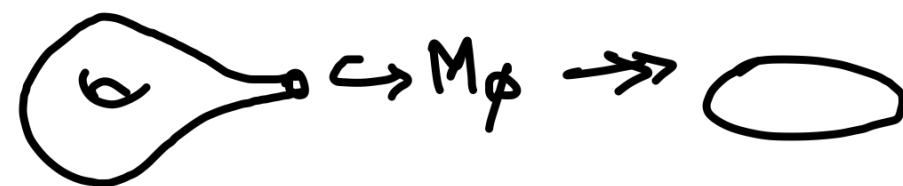
Complement is proj. rigid.



$(2,3)$
+



$$F_2 \hookrightarrow \Gamma \twoheadrightarrow F_1$$



iprc of a hyp. once punctured two back can be
equivalently stated in terms of dynamics on $\mathcal{X}(\pi_1(F), \text{PGL}(4, \mathbb{R}))$
at point corresponding to complete hyp. structure.

iprc of a hyp. once punctured two back can be
determined from roots of a polynomial associated to holonomy

$$\pi_1(M_\phi) \hookrightarrow \text{PSL}(2, \mathbb{C}) \cong \text{PSO}(3,1) < \text{PGL}(4, \mathbb{R})$$

Ideas and Techniques

Study deformation space at infinitesimal

level $T_{[p]} X(\Gamma, PGL(4, \mathbb{R})) \cong H'(\Gamma; \mathfrak{sl}_4 \mathbb{R})$
(Weil int. rig.)

Try understand deformations of boundary torus,

investigate $H'(M; \mathfrak{sl}_4 \mathbb{R}) \xrightarrow{\text{res}} H'(\partial M; \mathfrak{sl}_4 \mathbb{R})$
image is 3-dimensional the $\frac{1}{2}$ -live $\frac{1}{2}$ dies

Numerically investigate using SnapPy, interval arithmetic, etc.
Plot using computers.

Thank you for your time!

