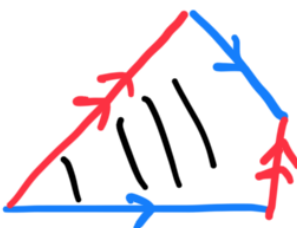


Σ χ $\mathcal{M}$ Δ $\angle$ ε $\sqsubset$ $\neg$ $\sqsupset$

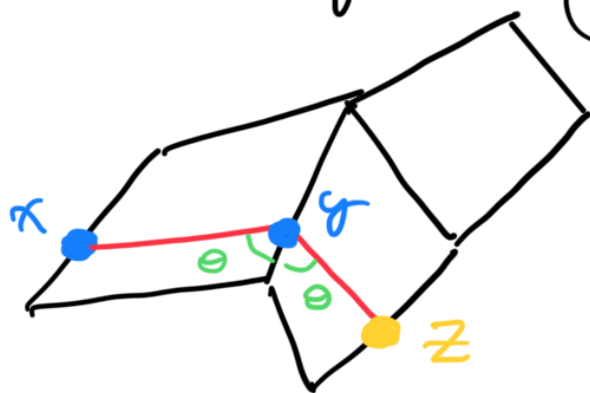


On  (Charles Daly & Fabi Londer)
(Max Planck Institute in Leipzig)

13.03.26 - Universitat Autònoma
de Barcelona

Union of two games

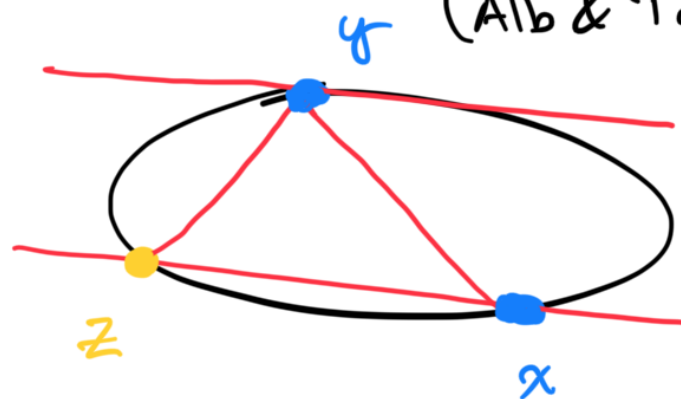
1. Tiling Billiards (Light?)



$$xy \mapsto yz$$

Angle (Similarity)

2. Symplectic Billiards (Alb & Tab '17)

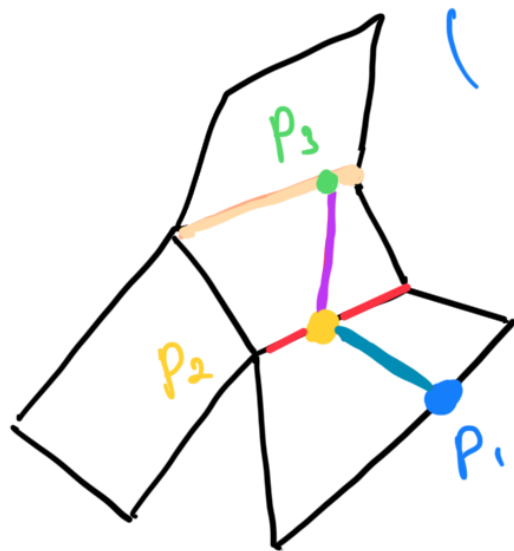


$$xy \mapsto yz$$

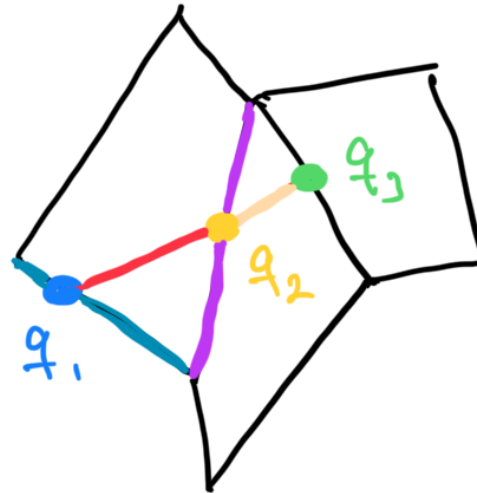
Parallel (Affine)

Symplectic Tiling Billiards

(Schwarz '23)



$$(P_1, q_1) \rightarrow (P_2, q_2) \rightarrow (P_3, q_3)$$



P_2 : Draw line through P_1 $\parallel$ to q_1 edge

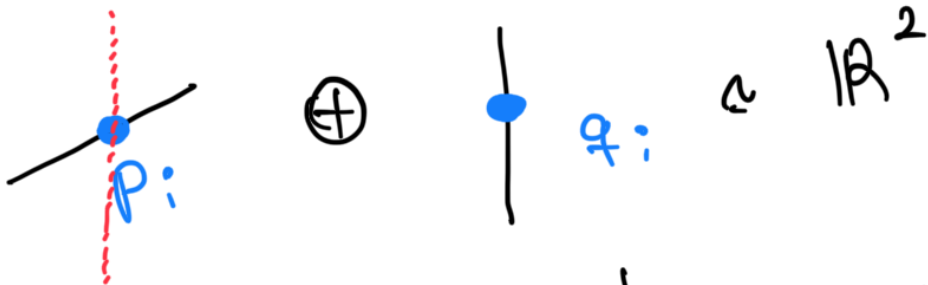
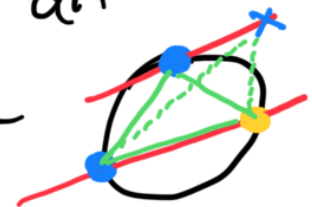
q_2 : Draw line through q_1 $\parallel$ to P_2 edge

P_3 : Draw line through P_2 $\parallel$ to q_2 edge

q_3 : Draw line through q_2 $\parallel$ to P_3 edge

Some Remarks

- Called symplectic because there's an area form floating around somewhere
- Requirs edges are transverse



- Breaks when hit vertex

Some More Remarks

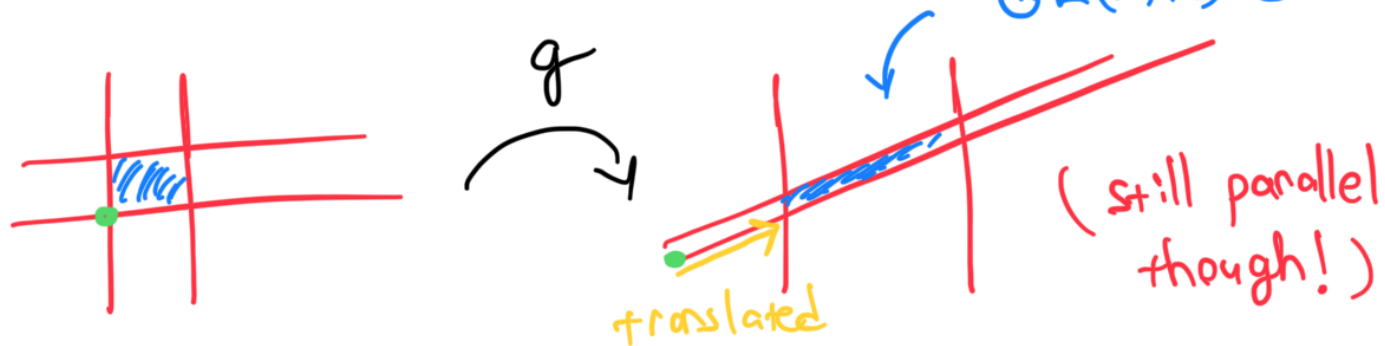
The symmetries of the game are affine in nature as the game required only words like 'contained', 'edge', 'parallel'. Specifically if (T_A, T_B) are tilings, the dynamics are isomorphic to that played on (g^{T_A}, g^{T_B})

Two Dimensional Affine Geometry

$X = \mathbb{A}^2$ (the plane but forget origin)

$G = \text{Aff}(2, \mathbb{R})$ group of translations
 $\mathbb{R}^2 + \text{General linear group}$

$$\cong GL(2, \mathbb{R}) \ltimes \mathbb{R}^2$$



Affine Symmetry

	$G = \text{Isom}(\mathbb{R}^2)$	$G = \text{Aff}(2, \mathbb{R})$
length	✓	✗
angle	✓	✗
area	✓	✗
orthogonal proj	✓	✗
parallelism	✓	✓
convexity	✓	✓
bary centers	✓	✓

Affine structures on surfaces

def: An affine structure on a surface S is an atlas of charts $\phi_\alpha: U_\alpha \xrightarrow{\subset S} \mathbb{A}^2$ so that coordinate changes are locally restrictions of affine transformations.



Observations

Given such a structure on S , the surface inherits the local geometry of $\mathbb{A}^2$. One can define notions of lines (geodesics), parallel, convexity, etc.

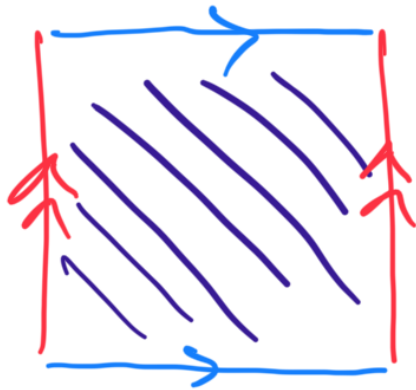


(Complete) Affine Surfaces

def: An affine surface is called complete if any geodesic can be extended indefinitely in both directions for all time.

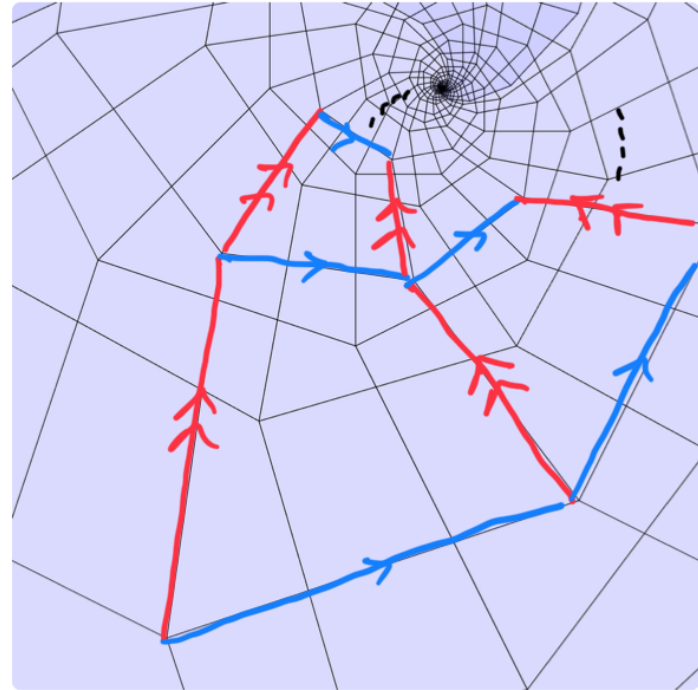
thm: An affine surface is complete if it is quotient A^2/Γ where Γ is discrete subgroup of affine transformations acting properly discontinuously and freely

Examples of Complete & Incomplete



&

$\mathbb{R}^2 / \langle \text{two translations} \rangle$



quadrilateral with edges
identified by two commuting
similarity transformations

Classification of Complex Affine Structures

(Baues & Goldman '05)
(Goldman '25)



or



theorem: The deformation space of complex
affine structures on T^2 is homeomorphic to
the plane. The mapping class group acts by
the standard $SL(2, \mathbb{Z})$ -action on $\mathbb{R}^2$ where the
fixed origin corresponds to the Euclidean structure.

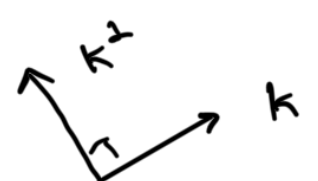
Classification continued

Every complete affine torus determined by single vector $\vec{k} = (k_1, k_2) \in \mathbb{R}^2 \simeq$ Deformation space of complete affine tori

$$\pi_1 \left(\begin{array}{c} \text{blue circle } \alpha \\ \text{red circle } \beta \end{array} \right) \xrightarrow{\text{hol } \vec{k}} \text{Aff}(2, \mathbb{R})$$

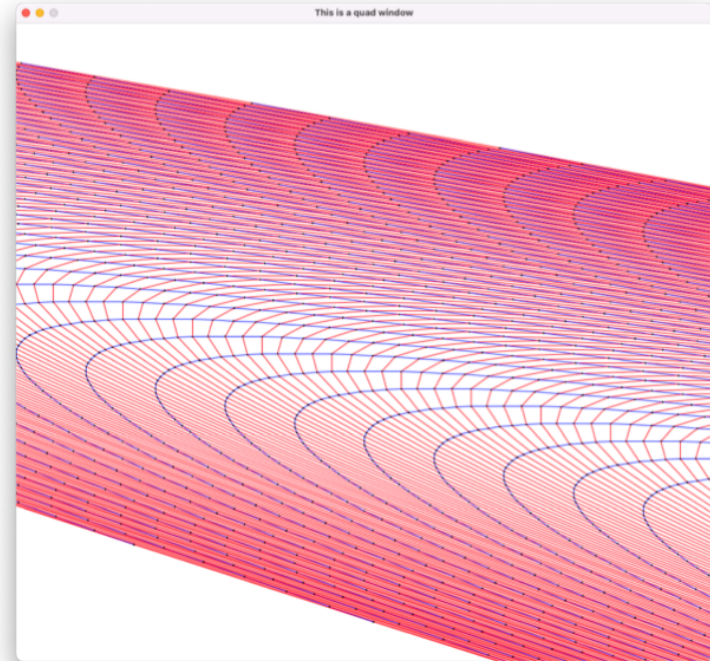
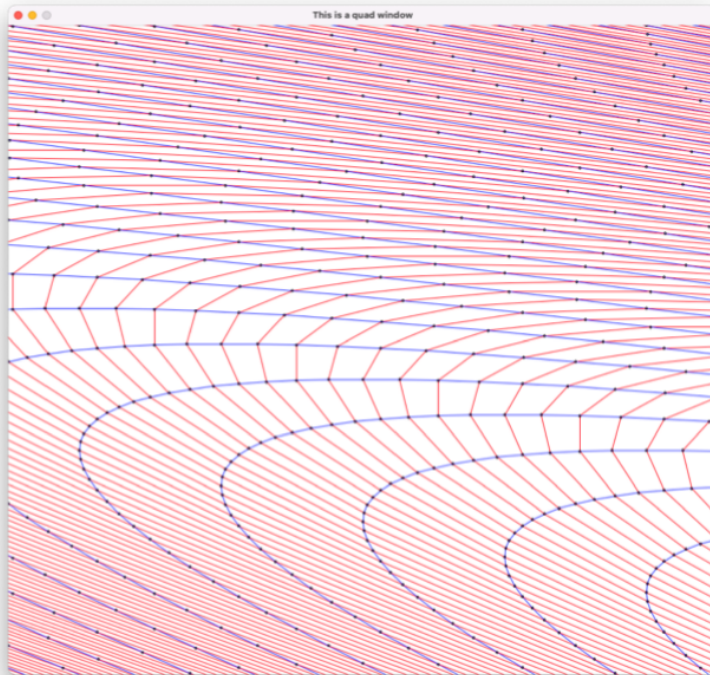
$$n \alpha + m \beta \xrightarrow{\gamma} \begin{aligned} \text{lin}(\gamma) \vec{v} &= \vec{v} + (\gamma \cdot \vec{k}) (\vec{v} \cdot \vec{k}) (-\vec{k})^\perp \\ \text{trans}(\gamma) &= \gamma + \frac{1}{2} (\gamma \cdot \vec{k})^2 (-\vec{k})^\perp \end{aligned}$$

Holonomy Observations

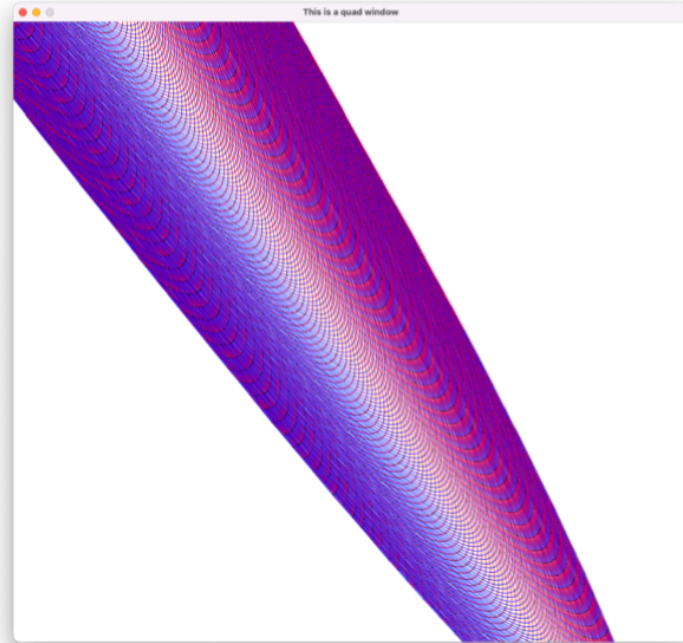
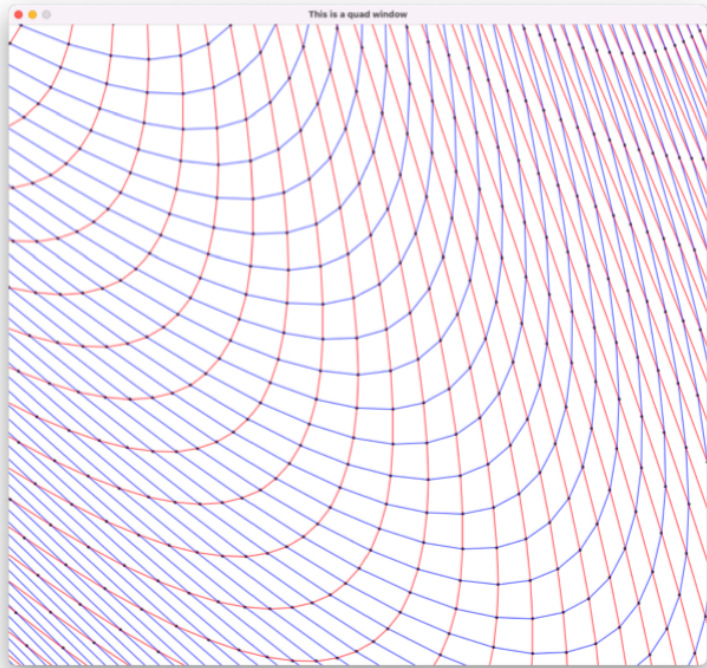
- Invariant vector field generated by $k^\perp$
 on T^2 can always go in that direction. To the right vs left also makes sense, but not angle.

- Invariant one form $\ell(\vec{v}) := \langle \vec{v}, \vec{k} \rangle$
leaves generated by flow of invariant vector field.
- If $\vec{k} \in \mathbb{Q}^2$, then holonomy contains pure translations.
Construct convex quadrilateral fundamental domains!
$$\text{lin}(\gamma) \vec{v} = \vec{v} + (\gamma \cdot \vec{k}) (\vec{v} \cdot \vec{k}) (-\vec{k})^\perp$$

Some Examples $(k_1, k_2) = (1/4, 1)$



Some Examples $(k_1, k_2) = (-3/5, -2/5)$



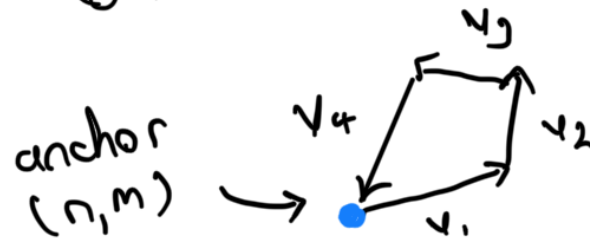
One more example



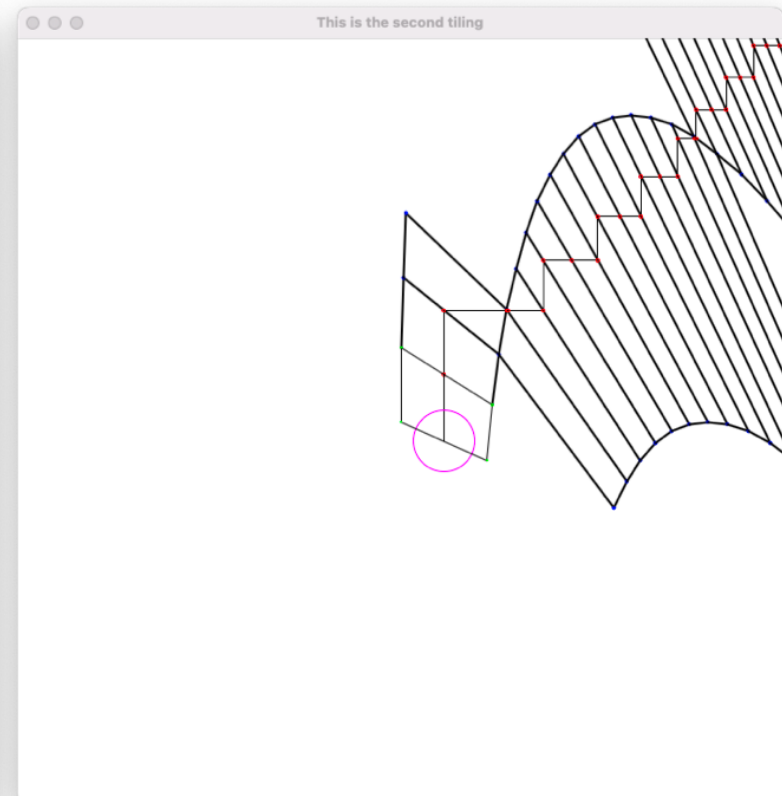
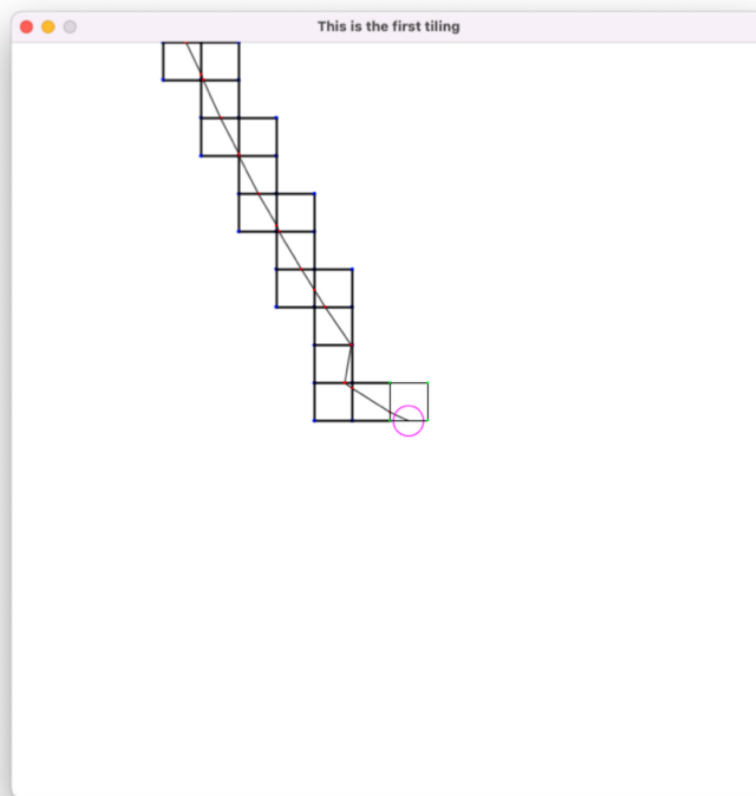
Käthe-Kollwitz -
Straße 66, 04109,
Leipzig

Playing on rational tor?

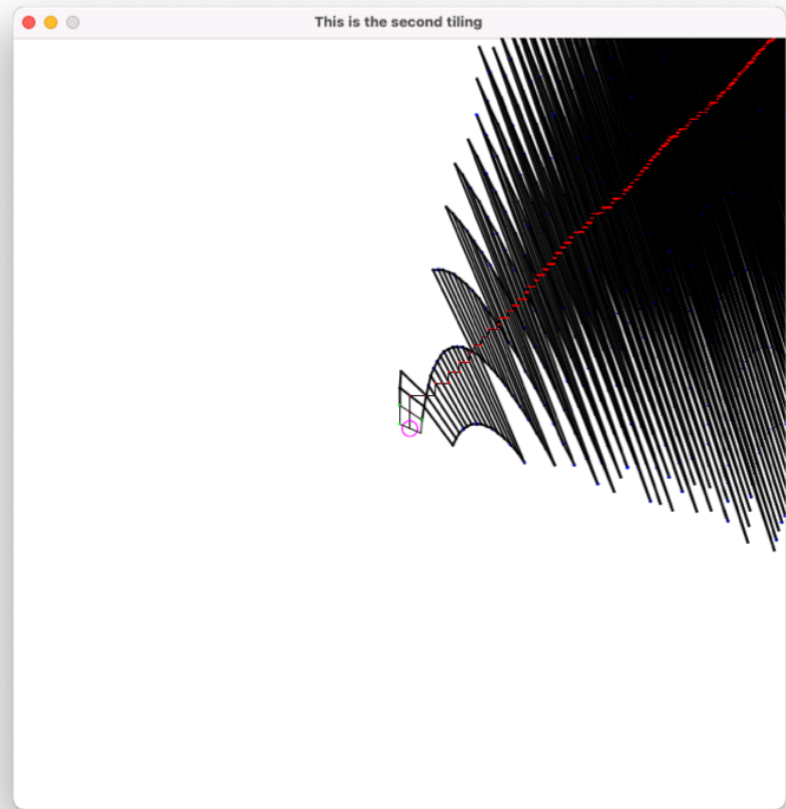
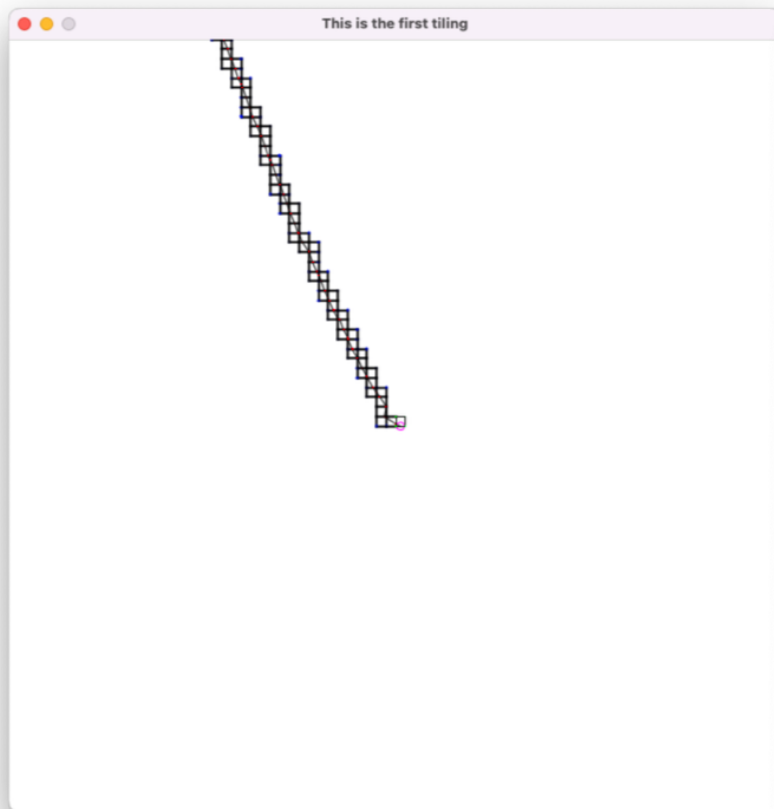
- Let one tile be Euclidean
- For other tile, assume $k_1, k_2 \in (\mathbb{Q}^*)^2$
(This guarantees transversality
in long-run)
- Orient our tiles counter clockwise



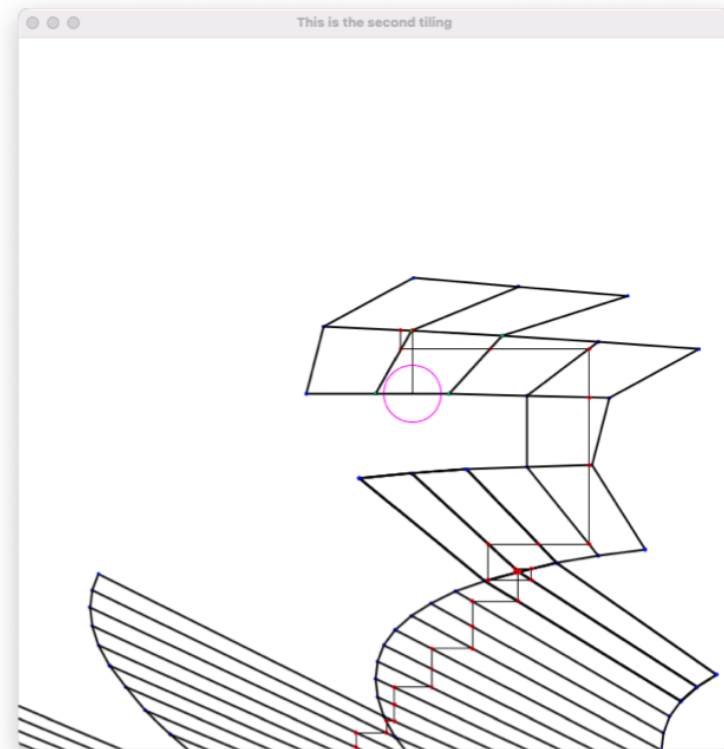
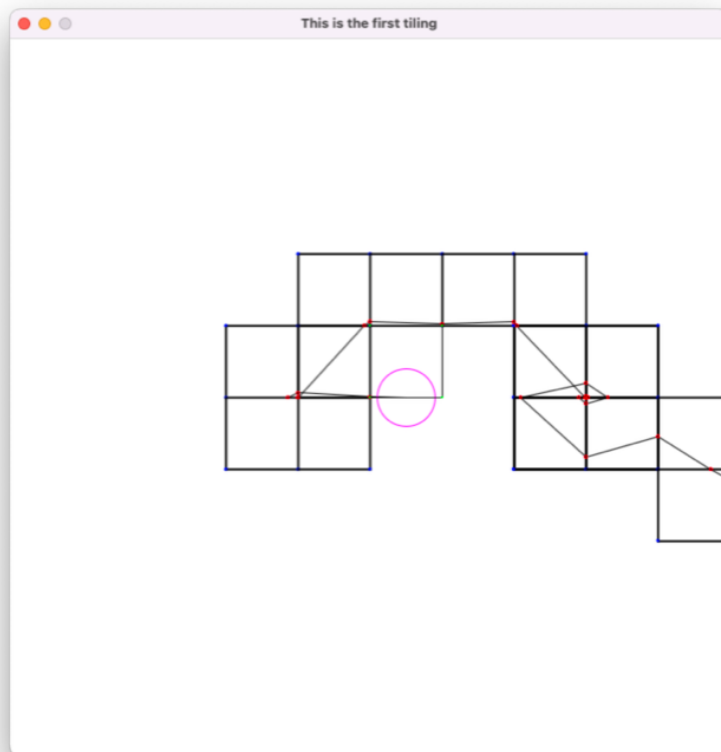
Some orbits $(k_1, k_2) = (1, 1/4)$



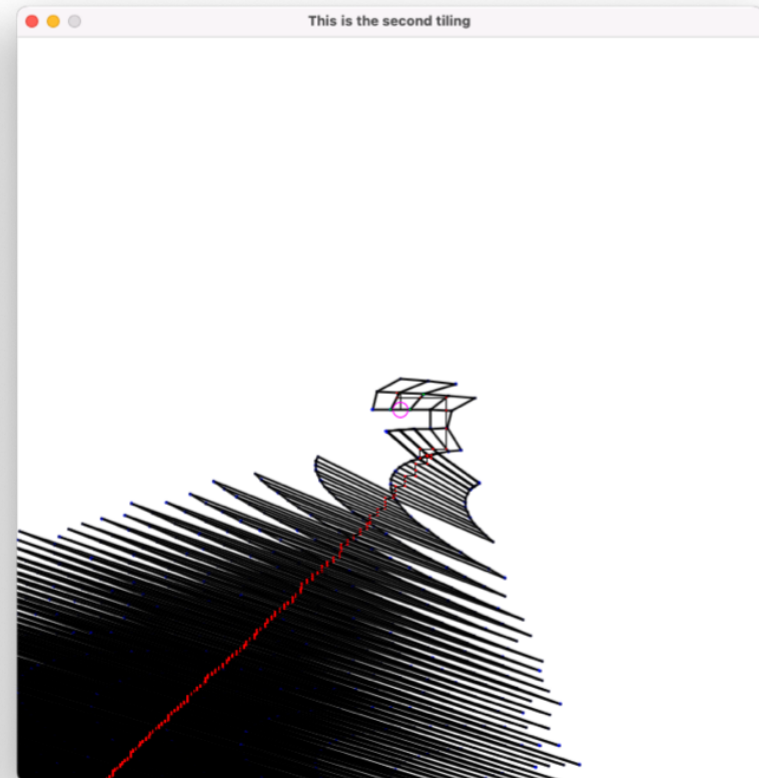
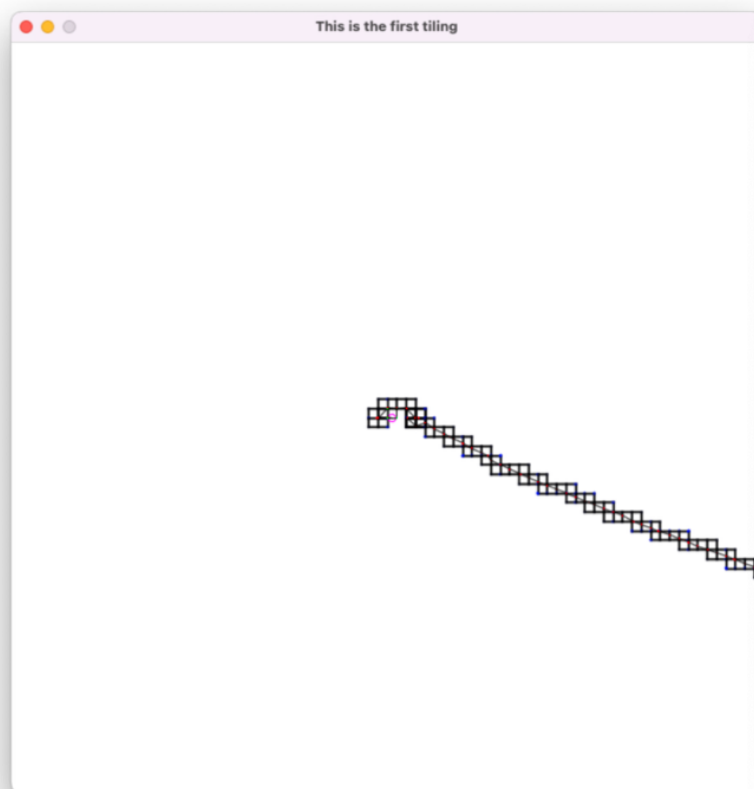
Some orbits $(k_1, k_2) = (1, 1/4)$



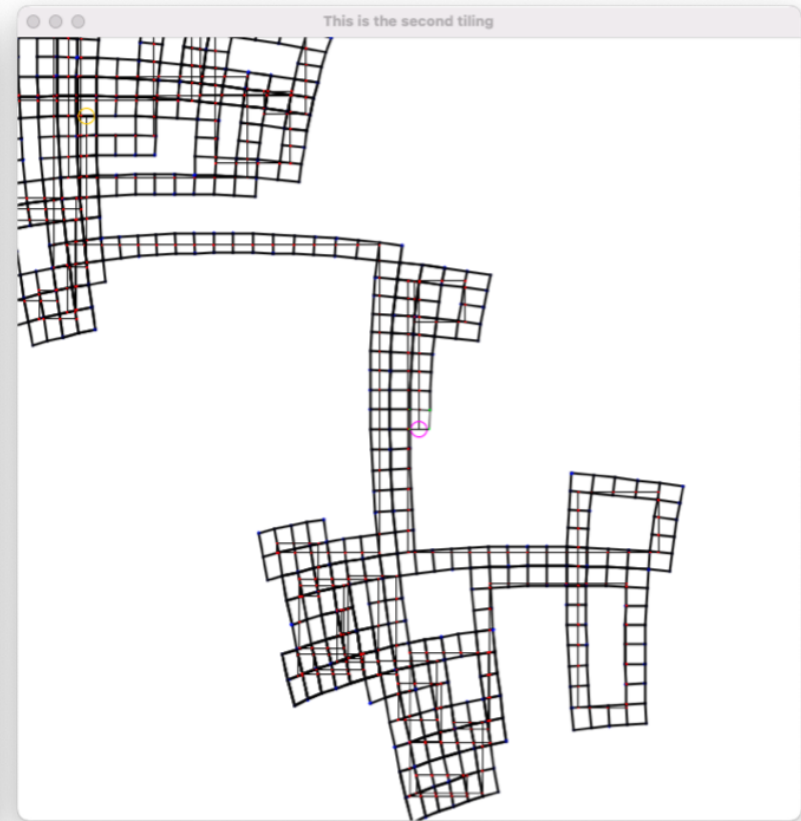
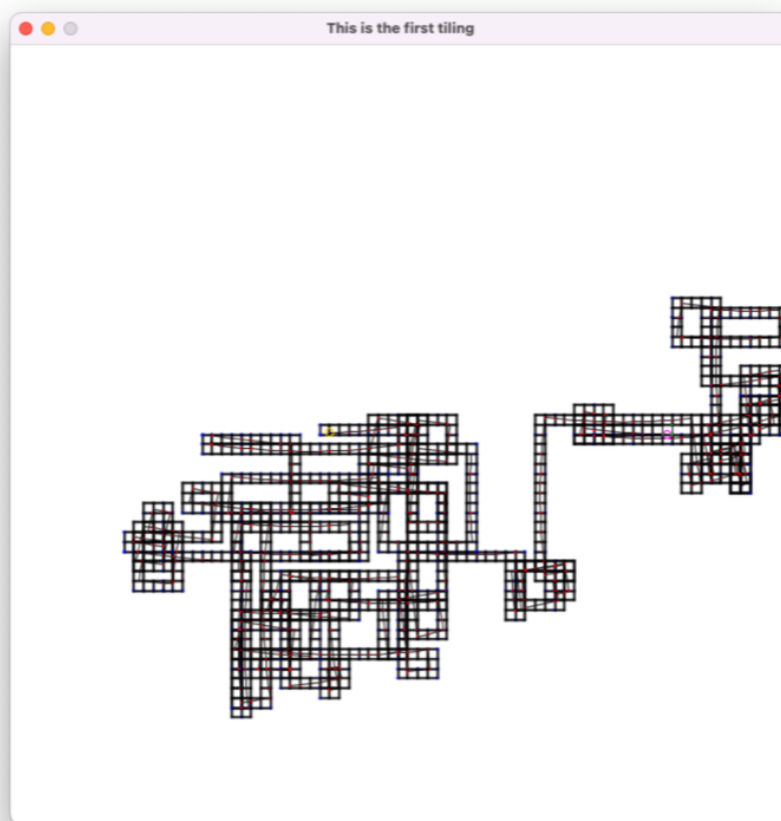
Some orbits $(k_1, k_2) = (1/4, 1)$



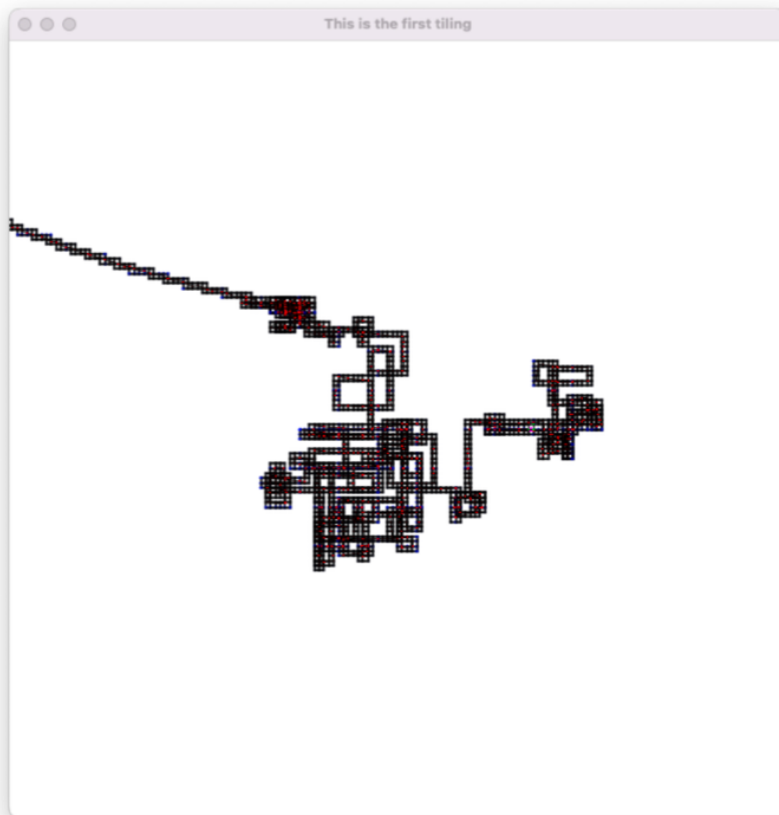
Some orbits $(k_1, k_2) = (1/4, 1)$



Some orbits $(k_1, k_2) = (1/4, 1/4)$



Some Orbits $(k_1, k_2) = (1/4, 1/4)$

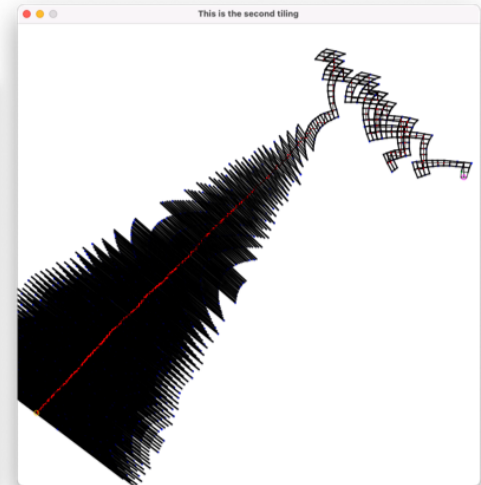
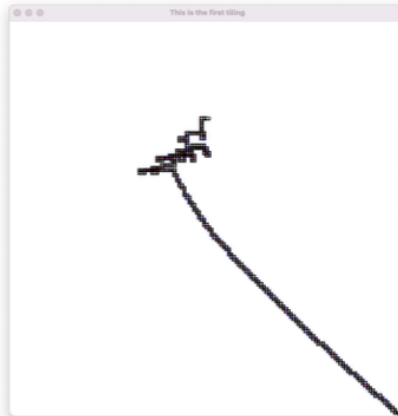


Conclusion :

Seem to generically diverge provided $\vec{K} \neq \vec{0}$. However, does not seem to be a way to determine after how many iterates. But the idea is clear for sufficiently 'far away' non-Euclidean tiles

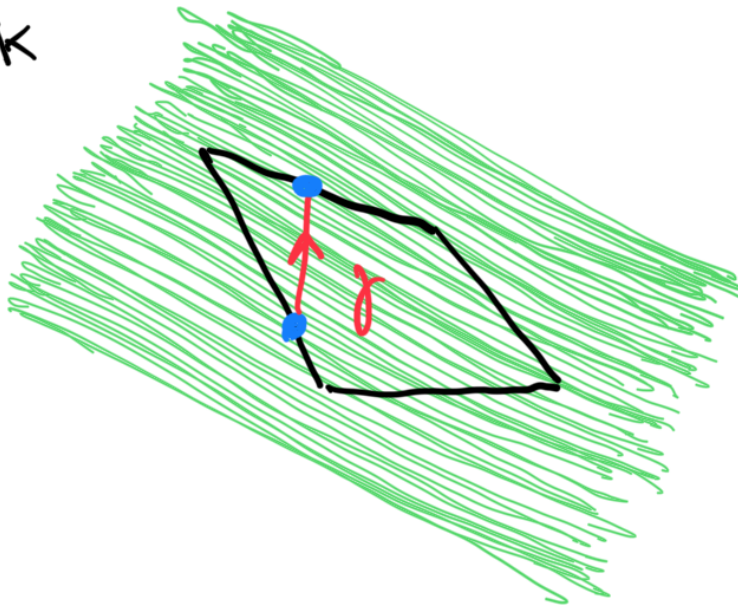
Theorem (DL: Work in Progress '26)

For any $\vec{k} \neq 0 \in (\mathbb{Q}^*)^2$, there exists a sufficiently large $C_{\vec{k}} > 0$ so that any tile anchored at (n, m) with $(n, m) \cdot \vec{k} > C_{\vec{k}}$ admits divergent orbits.



Way to Measure Divergence

To each orbit, can assign a #
which measures how far along $\vec{K}$ moving.

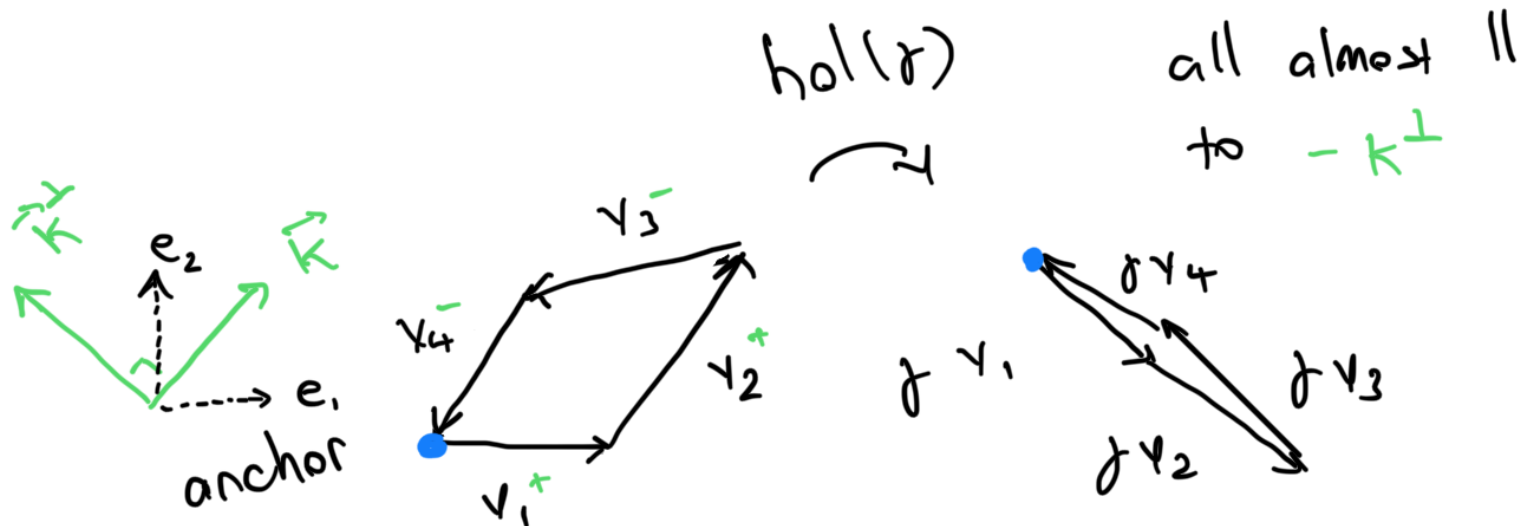


$$\int_{\sigma} \omega > 0$$

(oriented) foliation
by leaves of ω .

key Observation

As $\gamma = (n, m)$ becomes more parallel to $\vec{K}$, the tiles flatten out parallel to $K^\perp$.

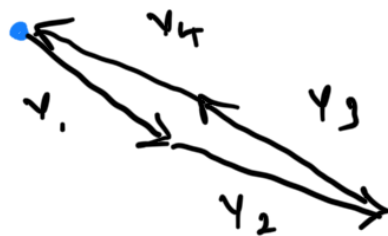


Why Tiles Flatten

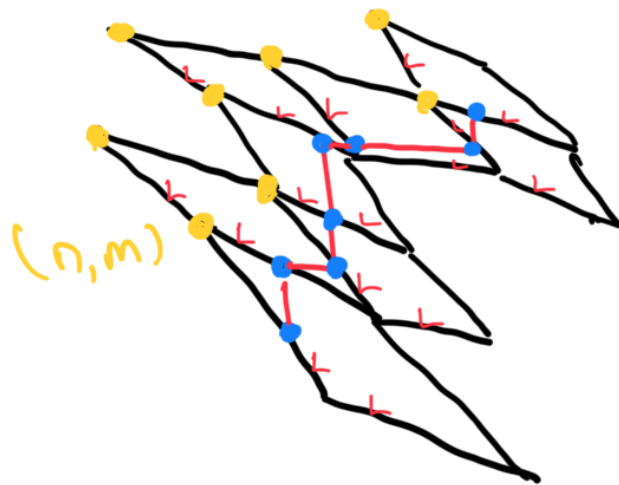
Recall $\text{hol}(f) \vec{v} = \vec{v} + (f \cdot \vec{K}) (\vec{v} \cdot \vec{K}) (-K^\perp)$

So when $(f \cdot \vec{K}) \gg 0$ we have

$\text{hol}(f) \vec{v}$ is approximately parallel to $\langle K^\perp \rangle$.



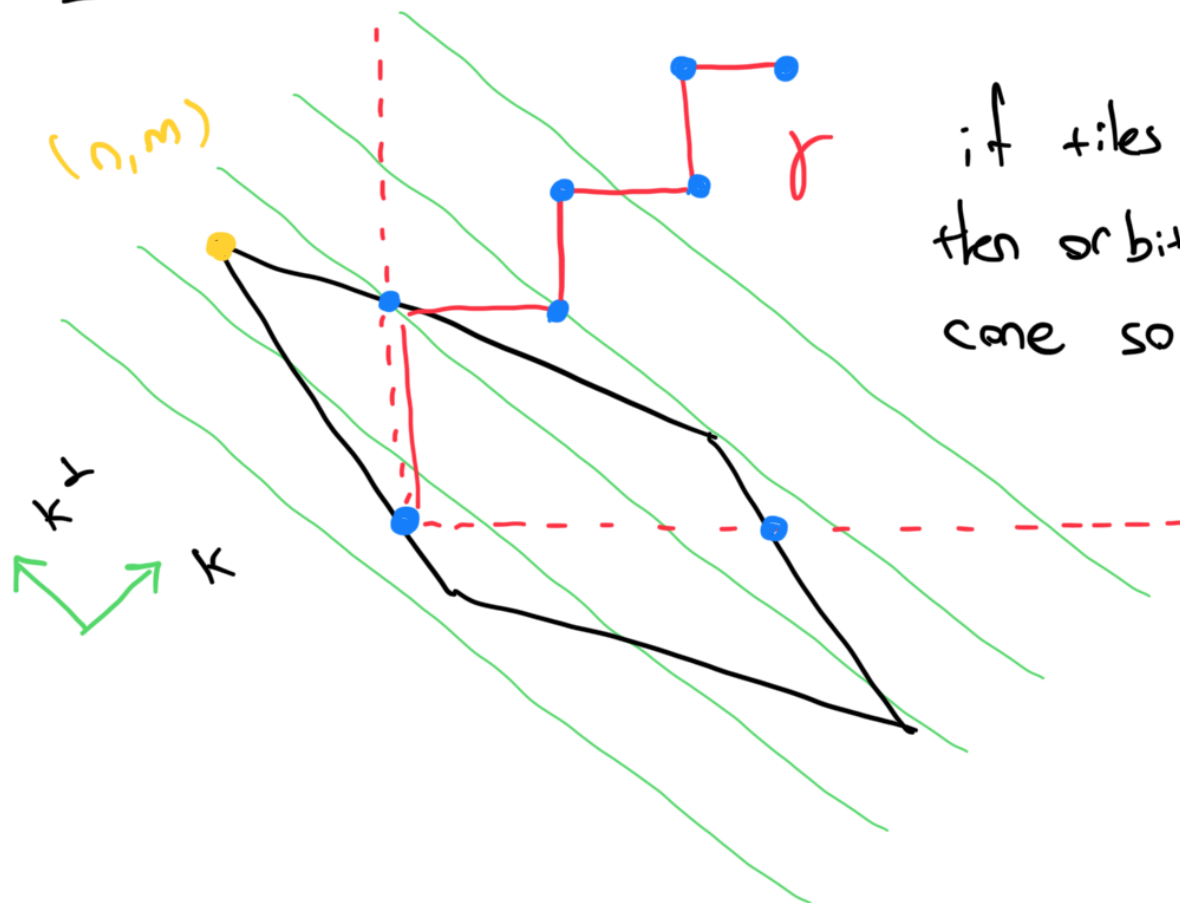
Move through Flat Tiles



if tiles remain flat,
then can only move in
one of two directions

↑
→ Anchors • (n, m)
determine how
flat a tile is.

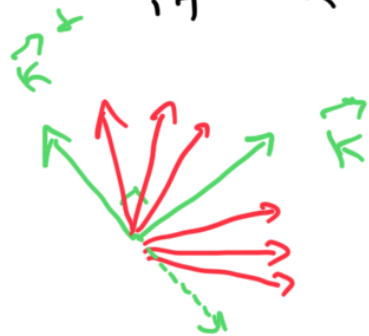
Want to Guarantee Tiles Remain Flat



if tiles remain flat
then orbits remain in
cone so $\int_{\gamma} \omega \rightarrow \infty$

Positive / Negative Directions

def: Say a vector $\vec{v}$ is positive / negative
if $\langle \vec{v}, \vec{k} \rangle$ positive / negative.



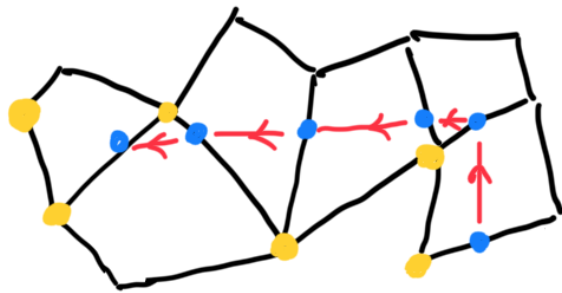
fan of positive directions

$$\langle \text{hol}_\gamma \vec{v}, \vec{k} \rangle = \langle \vec{v}, \vec{k} \rangle$$

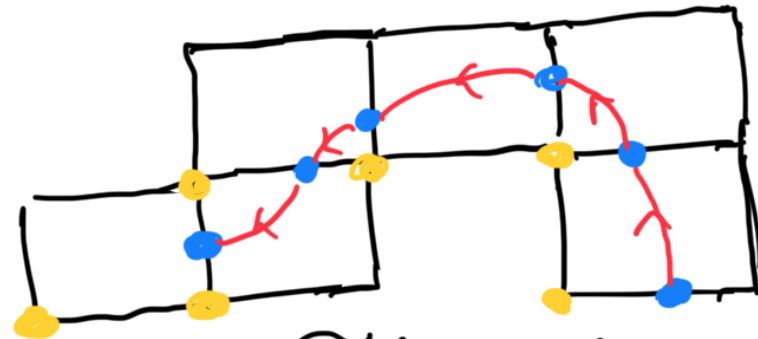
A loop $\gamma \in \pi_1(T^2)$ is positive iff

$\langle (n, m), k \rangle$ is positive where $\gamma = n\alpha + m\beta$.

Orbits to Loops



in A^2

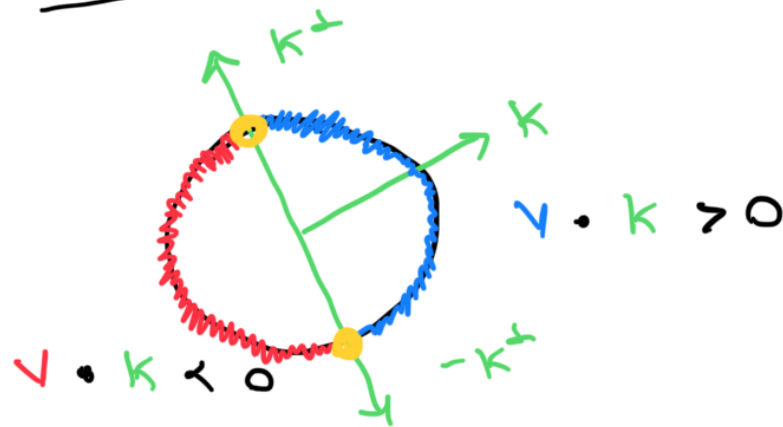


in $T^2 \approx \mathbb{R}^2$

Assign orbit holonomy

$$e_2 - e_1 - e_1 - e_2 - e_1 = \begin{pmatrix} -3 \\ 0 \end{pmatrix}$$

Parabolic Holonomy



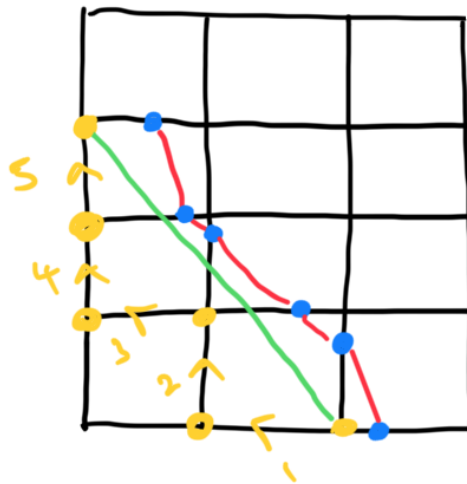
positive/negative
directions preserved
for all $\gamma \in \pi_1(T^2)$

Positive loops move positive directions towards $-k^\perp$
and negative directions towards $k^\perp$.

Control on Tile Shape

if $\vec{k} = (\frac{a}{c}, \frac{b}{c})$ then after $|a| + |b|$ moves, at worst, a tile will get translated in only positive directions.

orbit gets assigned
loop $\gamma = (-2, 3)$



$$\vec{k}^\perp = (-2, 3)$$

$$\vec{k} = (3, 2)$$

Tiles Must Flatten

If picked a tile at (n, m) that stays sufficiently flat for $|a| + |b|$ -moves, then at worst, after these moves the



then proceed argument again.
Because $\int_{\gamma} w \rightarrow \infty$, tiles must flatten.

Future Directions

- Try and show this behavior is generic
i.e. the measure of configurations which
do not diverge is trivial
- Implement this for $k \in \mathbb{Q}(\sqrt{2})^2$. All of
this is affine! Only algebraic operations are
 $+, -, \cdot, \div$.
- Better understand the case where $\vec{K}_1 \neq 0$ and
 $\vec{K}_2 \neq 0$

Thank you for your time!

